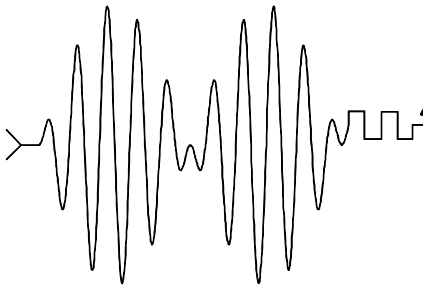
CMV586DX133, CMV486DX100HR and CMV486DX66HR cpuModule™ User's Manual

BIOS Versions 4.7x



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CMV586DX133, CMV486DX100HR and CMV486DX66HR cpuModule™ User's Manual

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CHAPTER 1: INTRODUCTION

This manual is meant for users developing with the CMV586DX133, CMV486DX100HR or CMV486DX66HR cpuModules. It contains information on hardware and software of the cpuModule.

The manual is organized as follows:

Chapter 1: **Introduction**

Introduces main features and specifications.

Chapter 2: **Getting Started**

Provides abbreviated instructions to get started.

Chapter 3: **Connecting the cpuModule**

Provides information on connecting the cpuModule to peripherals.

Chapter 4: **Configuring the cpuModule**

Provides information on configuring hardware and software.

Chapter 5: **Using the cpuModule**

Provides information needed to develop applications for the cpuModule. The chapter includes general information on the cpuModule, plus detailed information on storing applications, using Virtual Devices and system functions, and using utility programs.

Chapter 6: **Hardware Reference**

Lists jumpers and their locations and mechanical dimensions.

Chapter 7: **Troubleshooting**

Offers advice on debugging problems with your system.

Chapter 8: **Warranty**

The CMV586DX133 / 486DX100HR / 486DX66HR cpuModules

The PC/104 cpuModules described in this manual are designed for industrial applications which require:

- software and hardware compatibility with the PC/AT world
- high-speed "number-crunching" operation
- low power consumption
- small physical dimensions
- high reliability
- good noise immunity

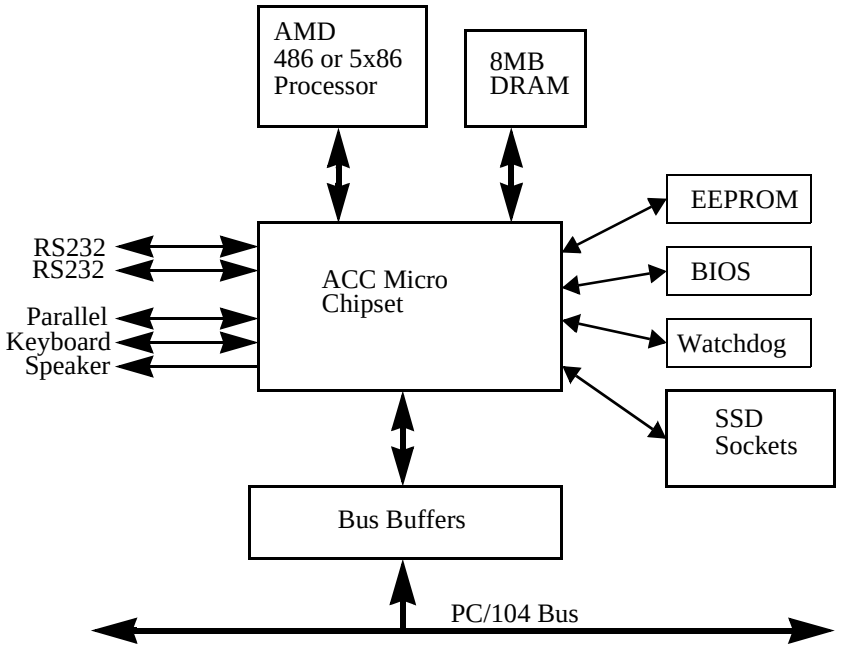
This cpuModule is highly integrated, combining all major functions of a PC/AT computer on one compact board. It integrates all primary I/O functions of a AT compatible computer:

- keyboard interface
- Bidirectional parallel port
- two RS232 serial ports
- Real Time Clock
- Speaker port

It also enhances standard AT-compatible computer systems by adding:

- two Solid State Disk sockets
- a non-volatile configuration EEPROM
- a Watchdog Timer

The figure below shows a simplified block diagram of the cpuModule:



You can easily customize the cpuModule by stacking PC/104 modules such as video controllers, modems, LAN controllers, or analog and digital data acquisition modules. Stacking PC/104 modules on the cpuModule avoids expensive installations of backplanes and card cages and preserves the module's compactness.

A PC compatible BIOS is also implemented in the cpuModule. This BIOS supports ROM-DOS and MS-DOS operating systems. Drivers in the BIOS allow booting from floppy disk, hard disk, Solid State Disk, or DiskOnChip, thus enabling the system to be used with traditional disk drives or non-mechanical drives.

The cpuModule and BIOS are also compatible with most real-time operating systems for PC compatible computers, although these may require creation of custom drivers to use the SSD, EEPROM, and watchdog timer.

For industrial applications, a set of BIOS functions have also been implemented which allow easy control of system hardware devices.

Specifications

CMV586DX133

- AMD Am5x86 microprocessor
- 133 MHz clock speed
- 3.3 V processor supply
- 16 KB on-chip cache memory
- Math coprocessor

CMV486DX100HR

- AMD Am486 microprocessor
- 100 MHz clock speed
- Extended temperature processor
- 3.3 V processor supply
- 16 KB on-chip cache memory
- Math coprocessor

CMV486DX66HR

- AMD Am486 microprocessor
- 66 MHz clock speed
- Extended temperature processor
- 3.3 V processor supply
- 16 KB on-chip cache memory
- Math coprocessor

DMA, Interrupts, Timers

- Six (6) DMA channels (8237 compatible)
- Fifteen (15) interrupt channels (8259 compatible)
- Three (3) counter/timers (8254 compatible)

Memory Configurations

- 8M bytes DRAM, installed

Solid State Disk

- two 32-pin sockets
- an SSD socket can hold one of the following Conventional SSD devices:

Device	Full Read/Write Access	128Kbytes	256Kbytes	512Kbytes	1Mbyte
Atmel 5V Flash	yes	yes	yes	yes	no
SRAM	yes	yes	no	yes	no
NOVRAM	yes	yes	no	yes	no
12V Flash (read-only)	no	yes	yes	no	no
EPROM	no	yes	yes	yes	yes
AMD 5V Flash	no	yes	no	yes	no

- an SSD socket can alternately hold one of the following devices which install using a

BIOS Extension:

Device	Full Read/Write Access	Maximum Number per cpuModule	Sizes
DiskOnChip 2000	yes	1	2 - 72 MB *
DiskOnChip 1000	yes	1	1MB, 2MB
MCSI PromDisk	yes	2	4MB, 8MB *

(*) Larger devices may be available in the future.

Peripherals

- Two full-duplex RS232 serial ports; baud rates from 50 to 115.2k baud (with 16450-type UARTs)
- Parallel port with SPP and bidirectional capability with selectable interrupts
- PC/AT standard keyboard port
- Speaker port
- Real Time Clock (requires user-supplied external battery for backup)
- Watchdog Timer

BIOS

- Directly supports Solid State Disk (SSD) and DiskOnChip
- User-configurable using built-in Setup program
- Supports serial link to host computer for keyboard, video, floppy, hard disk
- Can boot from floppy disk, hard disk, Solid State Disk, or serial port link (Virtual Devices)

Connections

- AT bus, per PC/104 specifications (64-pin J7, 40-pin J6)
- Serial port 1 connector (10-pin J3)
- Serial port 2 connector (10-pin J4)
- Parallel port connector (26-pin J2)
- Multifunction connector (10-pin J1)
- Auxiliary power connector (8-pin J8)

Physical Characteristics

- Dimensions: 3.6 x 3.8 x 0.6" (97 x 100 x 16mm)
- Weight (mass): 3.4 ounces (100 grams)
- PCB: 12-layer, mixed surface-mount and thru-hole

Operating environment

- Power supply: 5V +/- 5%
- 486DX100 processor operating temperature: -40 to +85 degrees C (with proper cooling) See ***486DX100/66 Processor Thermal Management*** on page 100
- 586DX133 processor operating temperature: -20 to +70 degrees C (with proper cooling) See ***5x86DX133 Processor Thermal Management*** on page 101
- Operating relative humidity: 0 to 95%, non-condensing
- Storage temperature : -55 to +125 degrees C.

Power Consumption

Exact power consumption depends on the peripherals connected to the board, the selected SSD configuration and the memory configuration.

The table below lists power consumption for typical configurations and clock speeds:

Typical Power Consumption				
Module	**Consumption**	**RAM**	**SSD**	**Coprocessor**
CMV586DX133 133MHz	1.75A (8.75W)	8MB	512kB Atmel Flash	Internal
CMV486DX100HR 100MHz	1.5A (7.5W)	8MB	512kB Atmel Flash	Internal
CMV486DX66HR 67MHz	0.84A (4.2W)	8MB	512kB Atmel Flash	Internal

For information on changing clock speeds, see ***Processor Clock Control*** on page 73.

CHAPTER 2: GETTING STARTED

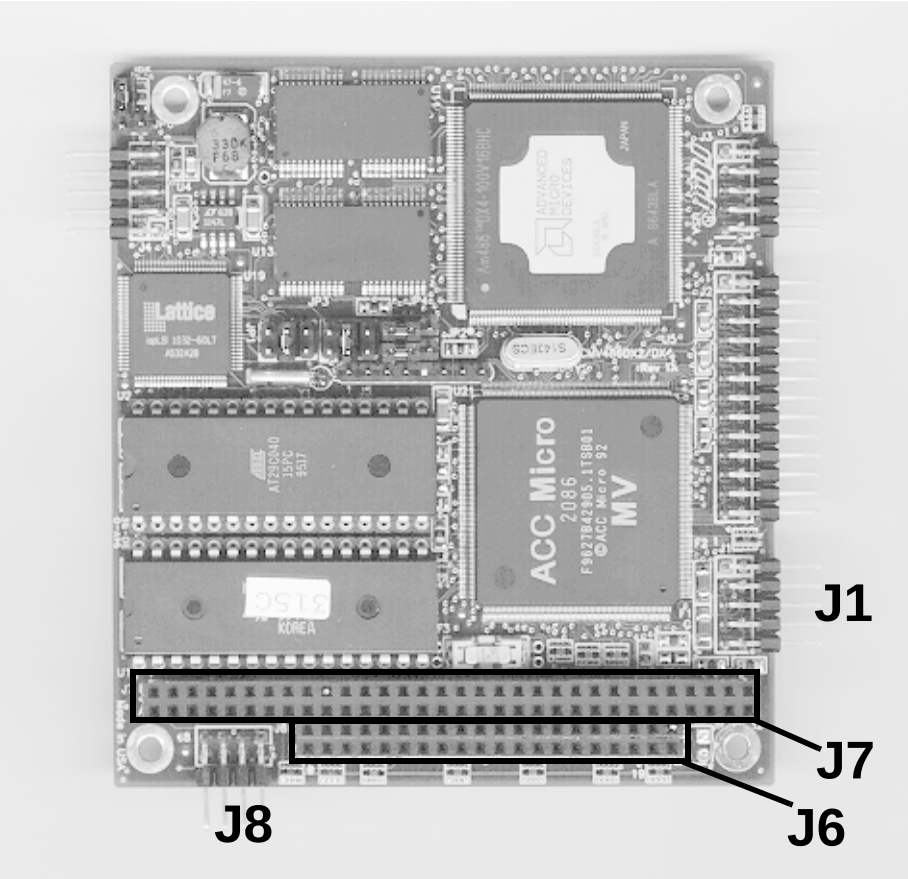
For many users, the factory configuration of the cpuModule can be used to get a PC/104 system operational. If you are one of these users, you can get your system up and running quickly by following a few simple steps described in this chapter. Briefly, these steps are:

- Connect power.
- Connect the utility cable.
- Connect a keyboard.
- Connect the PC/104 bus to a video card.

Refer to the remainder of this chapter for details on each of these steps.

Basic Connector Locations

The figure and table below show the connectors used in this chapter.



CMV Basic Connector Locations

Basic Connectors		
Connector	**Function**	**Size**
J1	Multifunction	10 pin
J6	PC/104 bus (AT)	40 pin
J7	PC/104 Bus (XT)	64 pin
J8	Auxiliary power	10 pin

For a complete listing of connectors, please refer to ***I/O Connections*** on page 26.

NOTE!	Pin 1 of each connector is indicated by a square solder pad on the bottom of the PC board and a white box silkscreened on the top of the board.

Default Configuration

The cpuModule comes from the factory with jumper JP5 installed. This forces the cpuModule to use the default Setup outlined in the following table. This configuration allows you to:

- boot from the Atmel SSD included in the first SSD socket or from floppy disk
- run the Setup program to configure the cpuModule

This procedure is described in more detail at the end of this chapter.

Highlights of Default Setup		
Item	**Setting**	**Controlled by:**
Boot device	Atmel SSD / Floppy	Setup
SSD size/type	Atmel 512KB Flash in first SSD socket	Setup + jumpers
Memory	8MB	Setup
Video	EGA/VGA	Setup
Floppy Drive 1	1.44M 3.5"	Setup
Floppy Drive 2	Not installed	Setup
Hard disk	Not installed	Setup

Cable Kits

For maximum flexibility, cables are not provided with the cpuModule. You may wish to purchase our cable kit for the cpuModule.

The XK-CM10 cable kit contains the following:

- Multifunction cable (keyboard socket, battery, reset, speaker)
- Two serial port cables (two - DIL10 to DSUB9)
- Parallel port cable (DIL26 to DSUB25)
- Power cable (DIL8 to wire leads)

Connecting Power

WARNING!	If you improperly connect power, the module will almost certainly be *damaged* or *destroyed*. Such damage is not warranted! Please verify connections to the module *before* applying power.

Power is normally supplied to the cpuModule through the PC/104 bus, connectors J6 and J7. If you are placing the cpuModule onto a PC/104 stack that has a power supply, you do not need to make additional connections to supply power.

If you are using the cpuModule without a PC/104 stack or with a stack that does not include a power supply, refer to ***Auxiliary Power, J8*** on page 28 for more details.

Connecting the utility cable

The Multifunction connector, J1, implements the following interfaces:

- AT keyboard
- Speaker output
- System reset input
- Battery input

To use these interfaces, you must connect to the Multifunction connector, making sure the orientation of pin 1 is correct. If you are using the Multifunction cable from our cable kit, the cable provides a small speaker, a 5-pin circular DIN connector for the keyboard, a pushbutton for resetting the PC/104 system, and a lithium battery to provide backup power to the Real Time Clock.

To connect individual devices to the Multifunction connector, please see ***Multifunction Connector, J1*** on page 33.

Connecting a Keyboard

You may plug a PC/AT compatible keyboard directly into the circular DIN connector of the Multi-function cable in our cable kit. Some newer keyboards may use a smaller "mini-DIN" connector; you will need an adapter to plug these keyboards into the cpuModule.

NOTE!	Many keyboards are switchable between PC/XT and AT operating modes, with the mode usually selected by a switch on the back or bottom of the keyboard. For correct operation with this cpuModule, you must select AT mode.

Connecting to the PC/104 Bus

Since this cpuModule does not include a video display controller, you will probably wish to stack the cpuModule with another card to add video. For example, you may add the CM112 utilityModule, which adds a VGA display controller with flat-panel support and a floppy and IDE hard drive controller, all on one PC/104 module.

The PC/104 bus connectors of the cpuModule are simply plugged onto a PC/104 stack to connect to other devices.

We recommend you follow the procedure below to ensure that stacking of the modules does not damage connectors or electronics.

WARNING!	Do not force the module onto the stack! Wiggling the module or applying too much pressure may damage it. If the module does not readily press into place, remove it, check for bent pins or out-of-place keying pins, and try again.

- Turn off power to the PC/104 system or stack.
- Select and install standoffs to properly position the cpuModule on the PC/104 stack.
- Touch a grounded metal part of the rack to discharge any buildup of static electricity.
- Remove the cpuModule from its anti-static bag.
- Check that keying pins in the bus connector are properly positioned.
- Check the stacking order; make sure an XT bus card will not be placed between two AT bus cards or it will interrupt the AT bus signals.
- Hold the cpuModule by its edges and orient it so the bus connector pins line up with the matching connector on the stack.
- Gently and evenly press the cpuModule onto the PC/104 stack.

Booting the cpuModule for the First Time

You can now apply power to the cpuModule. Depending on the VGA card you are using, you may see a greeting message from the VGA BIOS. You will then see:

- the cpuModule BIOS version information
- a message indicating jumper JP5 is installed and the default Setup is therefore being used
- a message requesting you press {F1} to continue booting using the default Setup, or press {Delete} to enter the Setup program

If you press {F1}, the cpuModule will try to boot from a 512KB Atmel Flash in the first SSD socket. If no device is found, it will try to boot from the first floppy drive.

If you press {Delete}, the cpuModule will enter Setup. Once you have configured the cpuModule using Setup, save your changes, turn off power, remove jumper JP5, and reboot.

If You Misconfigure the cpuModule

It is possible you may incorrectly configure the cpuModule using Setup. If this happens, you have several choices:

If video and keyboard are enabled:

- Re-boot the cpuModule.
- Immediately press and hold down the {Delete} key until the cpuModule enters Setup.

If video or keyboard are disabled:

- Insert jumper JP5. This will force the cpuModule to boot using the default configuration, which enables video and keyboard.
- Boot the cpuModule.
- Press the {Delete} key to enter Setup.

If the option **<DEL> for Setup** is disabled in the Advanced Setup screen:

- Insert jumper JP5. This will force the cpuModule to boot using the default configuration, which enables the {Delete} key to run Setup.
- Boot the cpuModule.
- Press the {Delete} key to enter Setup.

You can then reconfigure the cpuModule correctly using Setup.

For More Information

This chapter has been intended to get the typical user up and running quickly. If you need more details, please refer to the following chapters for more information on configuring and using the cpuModule.

CHAPTER 3: CONNECTING THE CPUMODULE

This chapter contains information necessary to use all connectors of the cpuModule.

I/O Connections

The cpuModule comes from the factory ready to connect to the peripherals shown in the following table.

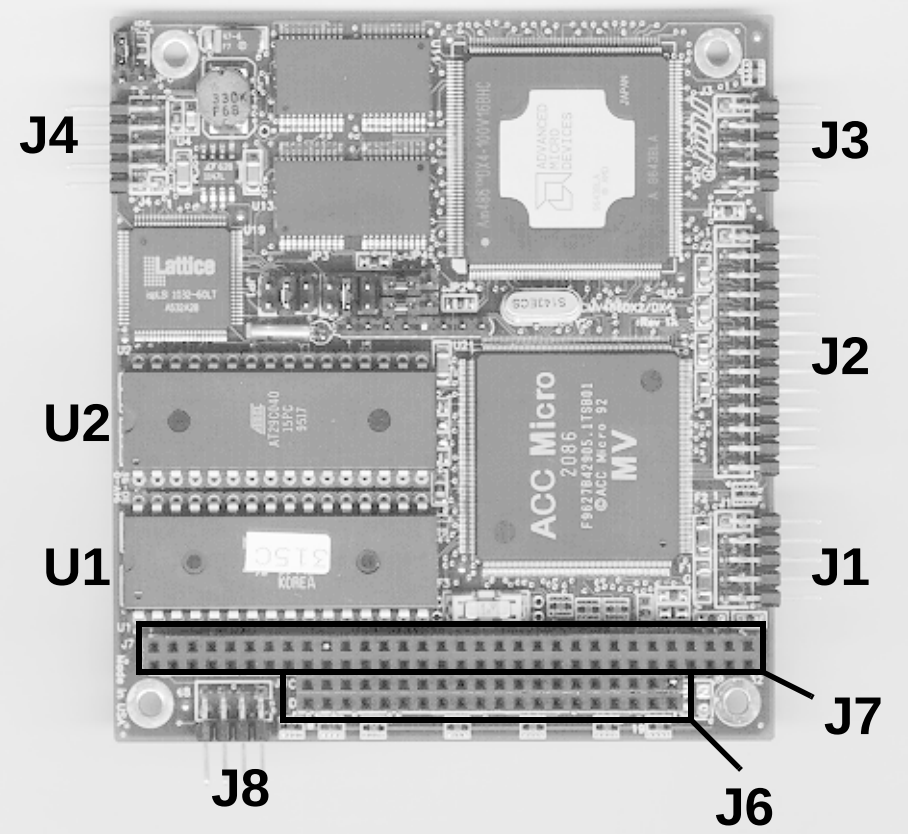
Default Peripheral Settings		
Item	**Setting**	**Controlled by**
Boot device	Atmel SSD / Floppy	Setup
SSD size/type	DiskOnChip @ D000	Setup + jumpers
Serial Port #1	3F8H	Setup
Serial Port #2	disabled	Setup
Parallel Port	Bi-directional at 378H	Setup
Video	EGA/VGA	Setup
Floppy Drive 1	1.44M 3.5"	Setup
Floppy Drive 2	Not installed	Setup
Hard disk	Not installed	Setup

If you are using peripherals compatible with this list, you do not need to configure any jumpers or software settings before connecting peripherals.

If you are using different peripherals, you may need to change the cpuModule settings. In that case, please see ***Configuring with the Setup program*** on page 47.

Connector Locations

The figure and table below show all connectors and the SSD sockets of the cpuModule.



CMV Connector Locations

Connectors		
Connector	Function	Size
J1	Multifunction	10 pin
J2	Parallel port	26 pin
J3	Serial port #1	10 pin
J4	Serial port #2	10 pin
J6	PC/104 bus (AT)	40 pin
J7	PC/104 bus (XT)	64 pin
J8	Auxiliary Power	8 pin

NOTE! Pin 1 of each connector is indicated by a square solder pad on the bottom of the PC board and a white box silkscreened on the top of the board.

Auxiliary Power, J8

WARNING!	If you improperly connect power, the module will almost certainly be *destroyed*. Please verify power connections to the module *before* applying power.

The power supply can be conveyed to the module either through the PC/104 bus (J6 and J7) or through the Auxiliary Power connector, J8.

Facing the connector pins, the pinout of the Auxiliary Power connector is:

7	5	3	1
GND	-5V		GND
+5V	-12V	+12V	+5V
8	6	4	2

NOTE!	-5VDC, +12VDC and -12VDC voltages are not used by the module, but are carried on the PC/104 bus connectors, J6 and J7.

Power Supply Protection

The cpuModule has protection circuitry which helps prevent damage due to problems with the +5V supply, such as:

- Reversed polarity
- Overvoltage
- Overcurrent

The circuitry includes a user-replaceable fuse, which is located near the PC/104 bus connector. This fuse is a:

- 2 amp Nano fuse
- Littelfuse part number R451 002

First Serial Port, J3

The first serial port is implemented on connector J3. The serial port is a PC compatible full-duplex RS232 port.

The I/O address and interrupt for the serial port can be individually selected using Setup. The available I/O addresses and interrupts are shown in the following table.

First Serial Port Settings		
I/O Address	**Default IRQ**	**Optional IRQs**
03F8H	IRQ4	IRQ3, IRQ5
02F8H	IRQ3	IRQ4, IRQ5

First Serial Port UART

The second serial port is implemented with a 16450-compatible UART (Universal Asynchronous Receiver/Transmitter). This UART is capable of baud rates up to 115.2 kbaud. Please refer to any standard PC-AT hardware reference for the register map of the 16450-type UART.

RS232 Serial Port

The second serial port operates only in full-duplex RS232 mode. It must therefore be connected to an RS232-compatible device.

The following table gives the connector pinout and shows how to connect to an external serial connector, either XT(DB25) or AT(DB 9) compatible.

Connector J3: Pin Assignments in RS232 Mode					
Pin	**Signal**	**Function**	**in/out**	**DB25**	**DB9**
1	DCD	Data Carrier Detect	in	8	1
2	DSR	Data Set Ready	in	6	6
3	RX	Receive Data	in	3	2
4	RTS	Request To Send	out	4	7
5	TX	Transmit data	out	2	3
6	CTS	Clear To Send	in	5	8
7	DTR	Data Terminal Ready	out	20	4
8	RI	Ring Indicate	in	22	9
9,10	GND	Signal Ground	--	7	5

Facing the connector pins, the pinout is:

9	7	5	3	1
GND	DTR	TXD	RXD	DCD
GND	RI	CTS	RTS	DSR
10	8	6	4	2

Second Serial Port, J4

A second serial port is implemented on connector J4. The serial port is a PC compatible full-duplex RS232 port.

The I/O address and interrupt for the serial port are individually selected using Setup. The available I/O addresses and interrupts are shown in the following table.

Second Serial Port Settings		
I/O Address	**Default IRQ**	**Optional IRQs**
02F8H	IRQ4	IRQ3, IRQ5
02E8H	IRQ3	IRQ4, IRQ5

Second Serial Port UART

The second serial port is implemented with a 16450-compatible UART (Universal Asynchronous Receiver/Transmitter). This UART is capable of baud rates up to 115.2 kbaud. Please refer to any standard PC-AT hardware reference for the register map of the 16450-type UART.

RS232 Serial Port

The second serial port operates only in full-duplex RS232 mode. It must therefore be connected to an RS232-compatible device.

The following table gives the connector pinout and shows how to connect to an external serial connector, either XT(DB25) or AT(DB 9) compatible.

Connector J4: Pin Assignments in RS232 Mode					
Pin	**Signal**	**Function**	**in/out**	**DB25**	**DB9**
1	DCD	Data Carrier Detect	in	8	1
2	DSR	Data Set Ready	in	6	6
3	RX	Receive Data	in	3	2
4	RTS	Request To Send	out	4	7
5	TX	Transmit data	out	2	3
6	CTS	Clear To Send	in	5	8
7	DTR	Data Terminal Ready	out	20	4
8	RI	Ring Indicate	in	22	9
9,10	GND	Signal Ground	--	7	5

Facing the connector pins, the pinout is:

9	7	5	3	1
GND	DTR	TXD	RXD	DCD
GND	RI	CTS	RTS	DSR
10	8	6	4	2

Parallel Port, J2

The parallel port is available on connector J2. You can use Setup to select its address and associated interrupt.

The pinout of the connector allows a ribbon cable to directly connect it to a DB25 connector, thus providing a standard PC compatible port.

The following tables lists the parallel port signals and explains how to connect it to a DB25 connector to obtain a PC compatible port.

NOTE! For correct operation, keep the length of the cable connecting the cpu-Module and parallel device less than 3 meters (10 feet).

Parallel Port Connector, J2				
Pin	**Signal**	**Function**	**in/out**	**DB25**
1	STB	Strobe Data	out	1
2	AFD	Autofeed	out	14
3	PD0	Printer Data 0 (LSB)	out	2
4	ERR	Printer Error	in	15
5	PD1	Parallel Data 1	out	3
6	INIT	Initialize printer	out	16
7	PD2	Printer Data 2	out	4
8	SLIN	Select printer	out	17
9	PD3	Printer Data 3	out	5
10	GND	Signal ground	--	18
11	PD4	Printer Data 4	out	6
12	GND	Signal ground	--	19
13	PD5	Printer Data 5	out	7
14	GND	Signal ground	--	20
15	PD6	Printer Data 6	out	8
16	GND	Signal ground	--	21
17	PD7	Printer Data 7 (MSB)	out	9
18	GND	Signal ground	--	22
19	ACK	Acknowledge	in	10
20	GND	Signal ground	--	23

21	BSY	Busy	in	11
22	GND	Signal ground	--	24
23	PE	Paper End	in	12
24	GND	Signal ground	--	25
25	SLCT	Ready To Receive	in	13
26	GND	Signal ground	--	26

Multifunction Connector, J1

The Multifunction connector on J1 implements the following functions:

- Speaker output
- AT keyboard
- System reset input
- Watchdog Timer output
- Battery Input
- Programming voltage input

The following table gives the pinout of the Multifunction connector.

Multifunction Connector, J1			
Pin	**Signal**	**Function**	**in/out**
1	SPKR+	Speaker output	out
2	SPKR-	Speaker output	out
3	RESET	External reset	in
4	WD	Watchdog output	out
5	KBD	Keyboard Data	in
6	KBC	Keyboard Clock	out
7	GND	Ground	--
8	KBP	Keyboard Power	out
9	BAT	Battery input	in
10	Vpp	Vpp for programming	in

Facing the connector pins, the pinout is:

9	7	5	3	1
BAT	GND	KBD	RESET	SPKR+
Vpp	KBP	KBC	WD	SPKR-
10	8	6	4	2

Speaker

A speaker output is available on two pins of the Multifunction connector. These outputs are controlled by a transistor to supply 0.1 watt of power to an external speaker. The external speaker should have 8 ohm impedance.

Keyboard

An AT compatible keyboard can be connected to the Multifunction connector. Usually PC keyboards come with a cable ending with a 5-pin male ’DIN’ connector. The following table lists the relationship between the Multifunction connector pins and a standard ’DIN’ keyboard connector.

To ensure correct operation, check that the keyboard is either an AT compatible keyboard or a switchable XT/AT keyboard set to AT mode. Switchable keyboards are usually set by a switch on the back or bottom of the keyboard.

Keyboard Connector			
Pin	**Signal**	**Function**	**DIN**
5	KBD	Keyboard Data	2
6	KBC	Keyboard Clock	1
7	GND	Ground	4
8	KBP	Keyboard Power	5

System Reset

Pin 3 of the multifunction connector allows connection of an external pushbutton to manually reset the system. The pushbutton should be normally open, and connect to ground when pushed.

Watchdog Timer

The active-high Watchdog signal generated on the cpuModule is available on pin 4 of the multifunction connector.The Watchdog time-out period is 1.2 seconds. If the Watchdog timer is not reset within that period, it the Watchdog signal is asserted and the cpuModule is reset.

See ***Watchdog Timer Control*** on page 69 for more information on controlling the Watchdog Timer.

Battery

Pin 9 of the multifunction connector is the connection for an external backup battery (in the range 2.40V to 4.15V; typically 3.6V). This battery is used by the cpuModule when system power is removed, to:

- preserve the date and time in the Real Time Clock
- preserve information stored in Static RAM in the Solid State Disk

If you wish to back-up Static RAMs in the Solid State Disk, please note that:

- jumpers JP2 and JP4 must be correctly set;
  see ***Storing Applications On-board*** on page 74
- SSD backup requires considerable battery power;
  you may require a larger backup battery than supplied with the cable kit

Programming Voltage, Vpp

Pin 10 of the Multifunction connector is used when programming 12 volt Flash EPROMs in the SSD, or when reprogramming the BIOS. You must supply this pin with a programming voltage, Vpp, of 12VDC +/- 5% to program these devices.

Refer to ***Storing Applications On-board*** on page 74 and ***BIOS Build Utility (BIOSBLD.EXE)*** on page 91 for more information.

NOTE! Once programming voltage is applied to pin 10 of the Multifunction connector, it still must be enabled to the individual SSD sockets:

Jumper JP1 pins 5-6 enable programming voltage to SSD socket U1.

Jumper JP3 pins 5-6 enable programming voltage to SSD socket U2.

PC/104 Bus, J6 and J7

Connectors J6 and J7 carry signals of the PC/104 bus; these signals match definitions of the IEEE P996 standard. The following tables list the pinouts of the PC/104 bus connectors.

The following table lists the signals of the XT portion of the PC/104 bus.

PC/104 XT Bus Connector, J7		
Pin	**Row A**	**Row B**
1	N.C.	0V
2	SD7	RESETDRV
3	SD6	+5V
4	SD5	IRQ2
5	SD4	-5V
6	SD3	DRQ2
7	SD2	-12V
8	SD1	N.C.
9	SD0	+12V
10	IOCHRDY	(Keying pin)
11	AEN	SMEMW*
12	SA19	SMEMR*
13	SA18	IOW*
14	SA17	IOR*
15	SA16	DACK3*
16	SA15	DRQ3
17	SA14	DACK1*
18	SA13	DRQ1
19	SA12	REFRESH*
20	SA11	SYSCLK
21	SA10	IRQ7
22	SA9	IRQ6
23	SA8	IRQ5
24	SA7	IRQ4
25	SA6	IRQ3
26	SA5	DACK2*
27	SA4	TC
28	SA3	BALE

29	SA2	+5V
30	SA1	OSC
31	SA0	0V
32	0V	0V

The following table lists signals of the AT portion of the PC/104 bus.

PC/104 AT Bus Connector, J6		
Pin	**Row C**	**Row D**
1	0V	0V
2	SBHE*	MEMCS16*
3	LA23	IOCS16*
4	LA22	IRQ10
5	LA21	IRQ11
6	LA20	IRQ12
7	LA19	IRQ15
8	LA18	IRQ14
9	LA17	DACK0*
10	MEMR*	DRQ0
11	MEMW*	DACK5*
12	SD8	DRQ5
13	SD9	DACK6*
14	SD10	DRQ6
15	SD11	DACK7*
16	SD12	DRQ7
17	SD13	+5V*
18	SD14	MASTER*
19	SD15	0V
20	(Keying pin)	0V

Notes:

Keying pin positions are blanked to prevent misalignment of stacked modules. This is a feature of the PC/104 specification and should be implemented on all mating PC/104 modules.

Signals marked with (*) are active-low.

All bus lines can drive a maximum current of 6mA at TTL voltage levels.

PC/104 Bus Signals

The following table contains brief descriptions of the PC/104 bus signals.

Signal	I/O	Description
AEN	O	Address ENable: when this line is active (high), it means a DMA transfer is being performed and therefore the DMA controller has control over the data bus, the address bus, and the control lines.
BALE	O	Bus Address Latch Enable, active high. When active, it indicates that address lines SA0 to SA19 are valid.
DACKx*	O	DMA ACKnowledge x=0-7, active low, used to acknowledge DMA requests.
DRQx	I	DMA Request x=0-7: these are asynchronous lines used by peripheral devices to request DMA service. They have increasing priority from DRQ0 up to DRQ7. A DMA request is performed by setting the DRQ line high and keeping it high until the corresponding DACK line is activated.
ENDXFR*	I/O	This is the only synchronous signal of the PC/104 bus and it is active low. It indicates that the current bus cycle must be performed with 0 wait states. It is used only for 16-bit boards.
IOCHCHK*	I	I/O Channel Check, active low, indicates an error condition that cannot be corrected.
IOCHRDY	I	I/O Channel Ready: this line, usually high (ready) is pulled to a low level by devices which need longer bus cycles.
IOCS16*	I	I/O Chip Select 16-bit: this line, active low, is controlled by devices mapped in the I/O address space. It indicates they have a 16-bit bus width.
IOR*	O	I/O Read, active low, indicates when the devices present on the bus can send their information on the data bus.
IOW*	O	I/O Write, active low. When active, it allows the peripheral devices to read data present on the data bus.
IRQx	I	Interrupt Request: x = 2 to 15, active on rising edge. IRQ15 has top priority; the other lines have decreasing priority starting from IRQ14 down to IRQ2. An interrupt request is performed by changing the level of the corresponding line from low to high and keeping it high until the microprocessor has recognised it.
KEY	N/A	These locations contain mechanical keying pins to help prevent incorrect connector insertion.
LA23..LA17	O	These signals select a 128kbyte window in the 16Mbyte address space available on the bus.

MASTER*	I	During a DMA cycle, this active-low signal, indicates that a resource on the bus is about to drive the data and address lines.
MEMCS16*	I	Memory Chip Select 16-bit: this line, active low, is controlled by devices mapped in the memory address space and indicates they have a 16-bit bus width.
MEMR*	I/O	This active-low signal indicates a memory read operation. Devices using this signal must decode the address on lines LA23..LA17 and SA19..SA0.
MEMW*	I/O	This active-low signal indicates a memory write operation. Devices using this signal must decode the address on lines LA23..LA17 and SA19..SA0.
OSC	O	OSCillator: clock with a 70 ns period and a 50% duty cycle. It is a 14.31818MHz always presents.
REFRESH*	O	This line is active low and indicates that the current bus cycle is a DRAM refresh cycle. The refresh cycles are activated every 15 microseconds.
RESETDRV	O	This line, active high, is used to reset the devices on the bus, at power-on or after a reset command.
SA0..19	O	Address bits 0 to 19: these lines are used to address the memory space and the I/O space. SA0 is the least significant bit while SA19 is the most significant bit.
SBHE*	O	This active-low signal indicates a transfer of the most significant data byte (SD15..SD8).
SD8..15	I/O	Data bits: these are the high-byte data bus lines. SD8 is the least significant bit; SD15 the most significant bit.
SD0..7	I/O	Data bits: these are the low-byte data bus lines. SD0 is the least significant bit; SD7 the most significant bit.
SMEMR*	O	Memory Read command, active low.
SMEMW*	O	Memory Write command, active low.
SYSCLK	O	System Clock, 8.0MHz with a 50% duty cycle. Only driven during external bus cycles.
TC	O	Terminal Count: this line is active high and indicates the conclusion of a DMA transfer.

PC/104 Bus Termination

Termination of PC/104 bus signals is not recommended and may cause malfunctions of the cpuModule. If termination must be applied, it should be a series termination of a resistor and capacitor, not exceeding 40-60 ohms and 30-70 pF, between each signal and ground.

CHAPTER 4: CONFIGURING THE CPUMODULE

This chapter contains information to configure the cpuModule.

Topics covered in this chapter include:

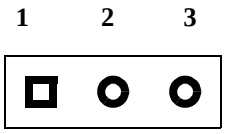
- Configuration jumpers
- Adding SSD Memory
- Configuring Using the Setup Program

Jumpers

Many cpuModule options are configured by positioning jumpers. Jumpers are labeled on the board as **"JP"** followed by a number.

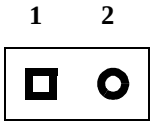
Some jumpers are three pins, allowing three settings:

- pins 1 and 2 connected (indicated as "1-2")
- pins 2 and 3 connected (indicated as "2-3")
- no pins connected.



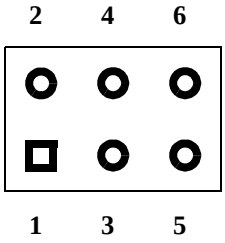
Some jumpers are two-pin, allowing two settings:

- pins 1 and 2 connected (indicated as "closed")
- pins 1 and 2 un-connected (indicated as "open")



Other jumpers are six-pin, allowing pins to be connected in one of three pairs:

- pins 1 and 2 connected (indicated as "1-2")
- pins 3 and 4 connected (indicated as "3-4")
- pins 5 and 6 connected (indicated as "5-6")



Six pin jumpers on this cpuModule *do not* use other positions, such as 1-3, 3-5, 2-4, or 4-6.

Installing SSD Memory

This section explains how to add devices to the cpuModule. This procedure is only necessary when you wish to add or change:

- Solid State Disk memory devices

Installing SSD Memory

You may wish to install SSD memory to use the cpuModule as a "diskless" stand-alone device.

Refer to ***Ways to Use the Solid State Disk Sockets*** on page 75 for more information on various SSD device types. Solid State Disk memories are placed in sockets U1 and U2. Generally, the device type and size in the first socket do not have to match the device type and size in the second socket.

When implementing the Solid State Disk, you must always follow these rules:

- The first socket must be filled before the second socket can be used;
- When using two SRAMs or two NOVRAMs, both devices must be the same size;
- When using *both* a Conventional SSD and a BIOS Extension device in the cpuModule, the Conventional SSD must go into the *first* socket;
- Generally, only one BIOS Extension device (like M-System's DiskOnChip or MCSI PromDisk) may be used at a time.

The following table lists possible configurations for the first socket of the SSD and the corresponding jumpers which must be set:

Jumpers for First SSD Socket, CMV586DX133, CMV486DX100HR or CMV486DX66HR						
Type	**Part**	**Operation**	**Capacity**	**JP1**	**JP2**	**Notes**
Atmel 5V Flash	29C010A	read/write	128KB	1-2	1-2	
	29C040A	read/write	512KB	1-2	1-2	
BIOS Extension Devices	DiskOnChip and PromDisk	read/write	to 12MB+	3-4	1-2	
NOVRAM	DS1645Y	read/write	128KB	3-4	1-2	
	DS1650Y	read/write	512KB	1-2	1-2	
SRAM	128KB	read/write	128KB	3-4	1-2	no backup
				3-4	2-3	battery backup
	512KB	read/write	512KB	1-2	1-2	no backup
				1-2	2-3	battery backup
12V Flash	28F010	read-only	128KB	5-6	1-2	programming
				3-4	1-2	read-only
	28F020	read-only	256KB	5-6	1-2	programming
				3-4	1-2	read-only
AMD 5V Flash	29F010	read-only	128KB	1-2	1-2	program or read
	29F040	read-only	512KB	1-2	1-2	program or read
EPROM	27C010	read-only	128KB	3-4	1-2	
	27C020	read-only	256KB	3-4	1-2	
	27C040	read-only	512KB	3-4	1-2	
	27C080	read-only	1MB	1-2	1-2	

The following table lists possible configurations for the second socket of the SSD and the corresponding jumpers which must be set:

Jumpers for Second SSD Socket, U2						
Type	**Part**	**Operation**	**Capacity**	**JP3**	**JP4**	**Notes**
Atmel 5V Flash	29C010A	read/write	128KB	1-2	1-2	
	29C040A	read/write	512KB	1-2	1-2	
BIOS Extension Devices	DiskOnChip and PromDisk	read/write	to 12MB+	3-4	1-2	
NOVRAM	DS1645Y	read/write	128KB	3-4	1-2	
	DS1650Y	read/write	512KB	1-2	1-2	
SRAM	128KB	read/write	128KB	3-4	1-2	no backup
				3-4	2-3	battery backup
	512KB	read/write	512KB	1-2	1-2	no backup
				1-2	2-3	battery backup
12V Flash	28F010	read-only	128KB	5-6	1-2	programming
				3-4	1-2	read-only
	28F020	read-only	256KB	5-6	1-2	programming
				3-4	1-2	read-only
AMD 5V Flash	29F010	read-only	128KB	1-2	1-2	program or read
	29F040	read-only	512KB	1-2	1-2	program or read
EPROM	27C010	read-only	128KB	3-4	1-2	
	27C020	read-only	256KB	3-4	1-2	
	27C040	read-only	512KB	3-4	1-2	
	27C080	read-only	1MB	1-2	1-2	

Configuring with the Setup program

The cpuModule Setup program allows you to customize the cpuModule's configuration. Selections made in Setup are stored on the board and read by the BIOS at power-on.

Setup for this cpuModule is called AT486. It is in three places:

- In the board's BIOS ROM, activated by the {Delete} key during boot
- In the Utility SSD provided in the first SSD socket
- On the utility disk supplied with the cpuModule.

The following section explains how to start Setup.

Starting Setup

You can run Setup one of several ways:

- Re-boot the cpuModule, and hold down the {Delete} key.
- Install default jumper JP5, boot the cpuModule, and press the {Delete} key.
- Boot the cpuModule, change to the Utility SSD, and run AT486.EXE.
- Boot the cpuModule, change to a diskette containing AT486.EXE, and run AT486.

When you are finished with Setup, save your changes and exit. If you are using Setup from the BIOS, the system will automatically reboot. Otherwise, you must manually do a hard reset, by pushing the reset pushbutton or cycling power.

If jumper JP5 was installed, make sure you turn off the cpuModule, remove the jumper, and reboot so the changes are recognized.

Using the Setup Program

All displays in Setup consist of two areas. The upper area lists the available selections. The lower area displays help messages which you should always read.

Main Menu Options

From the Main menu, you may choose:

- *Standard Setup* to access commonly used settings for the keyboard, floppy drives, hard disks, and SSD.
- *Advanced Setup* to access less-used settings for memory, the SSD, and error-handling.
- *Save Changes and Exit* to save your changes and exit Setup.
- *Exit Without Saving Changes* to leave Setup without saving your changes.

Normally you will use the first two selections to make changes to the cpuModule configuration, then use the *Save Changes and Exit* selection.

The version of Setup in the BIOS ROM will automatically cause a hard reset after you exit.

The DOS version of Setup (in the utility SSD and on floppy disk) has two added options:

- *Read settings from a File* which reads settings from a file on a disk
- *Save Settings to a File* which saves settings to a file on disk

These allow users to configure large numbers of modules without manually entering the settings each time.

The following sections describe each of these choices in detail.

Field Selection

You move between fields in Setup using the keys listed below.

Setup Keys	
Key	**Function**
↓	selects next field
↑	selects previous field
{TAB}	selects next field on the right or first field of next line
→	selects next value in field
←	selects former value in field
{ESC}	returns to main menu

Standard Setup Fields

The following is an alphabetical list of Standard Setup fields.

Standard Setup Fields		
Field	**Active keys**	**Selections**
Boot Device	← →	Selects the primary boot device. Possible selections: • Floppy Disk • SSD (Solid State Disk) • Hard Disk • This selects the device from which system boot is first attempted. • Hard Disk is used to boot from Hard Disk or a BIOS Extension device in an SSD socket.
Date	{0..9},{↵}	Sets the date with the format: • month / day / year • You must connect a backup battery, or this setting will be lost at power down.
Hard disk 1 type Hard disk 1 table	{0..9} {↵}	Selects the first hard disk type. Selections are: • Not Installed • Standard : (drives under 1024 Cylinders) • LBA: (drives over 1024 Cylinders) • Serial: for Virtual Devices mode. • When using Standard, manually enter parameters under Hard Disk 1 Table. • When using LBA, first select Standard, enter parameters under Hard Disk 1 Table, then change to LBA. New parameters will be calculated automatically.

Hard disk 2 type Hard disk 2 table	← → {0..9} {↵}	Selects the second hard disk type. Selections are: • Not Installed • Standard: (drives under 1024 Cylinders) • LBA: (drives over 1024 Cylinders) • When using Standard, manually enter parameters under Hard Disk 2 Table. • When using LBA, first select Standard, enter parameters under Hard Disk 2 Table, then change to LBA. New parameters will be calculated automatically.
Floppy Disk 1	← →	Selects the format of floppy disk 1: Selections are: • 360KB • 720KB • 1.2MB • 1.44MB • Serial (Used in Virtual Devices mode)
Floppy Disk 2	← →	Selects the format of floppy disk 2: Selections are: • 360KB • 720KB • 1.2MB • 1.44M
Serial Port J3	← →	Selects the address and type of the first serial port. Selections are: • RS232 at 03F8H (default) • RS232 at 02F8H • RS232 at 03E8H • RS232 at 02E8H • Disabled
Serial Port J4	← →	Selects the address of the second serial port. Selections are: • 03F8H • 02F8H (default) • 03E8H • 02E8H • Virtual Devices • Disabled
Keyboard	← →	Selects the keyboard mode. Selections are: • Disabled • ATkey: AT keyboard present • Serial (Used in Virtual Devices mode)

Memory Size	← →	Selects the size of installed dynamic RAM (DRAM). • Selections are4 Mbytes • 8 Mbytes (standard) Selecting an incorrect value may cause malfunctions.
Parallel Port	← →	Selects parallel port address Selections are: • 378h (default) • 278h • Disabled
Time	{0...9},{↵}	Sets the time with the format: • hours : minutes : seconds You must connect a backup battery or this setting will be lost at power down.
Video State	← →	Selects video mode. Selections are: • Monochrome • CGA, 40 by 25 • CGA, 80 by 25 • EGA/VGA • Serial (Used in Virtual Devices mode) • Not Installed Selecting 'Not Installed' will not prevent accesses to the video controller, which may cause unpredictable results.

Advanced Setup Fields

The following is a list of Advanced Setup fields.

Advanced Setup Fields		
Field	**Active keys**	**Selections**
SSD Device in U1	← →	Selects the device type installed in the first SSD socket. • The setting here must match the actual device installed in the socket. • Jumpers JP1 and JP2 must be set correctly.

SSD Device in U2	← →	Selects the device type installed in the second SSD socket. • The setting here must match the actual device installed in the socket. • Jumpers JP3 and JP4 must be set correctly.
SSD Window	← →	Selects the 32Kbyte address range where the SSD is mapped. Selections are: • D0000H to D7FFFH • D8000H to DFFFFH • E0000H to E7FFFH • E8000H to EFFFFH When selecting the address range, you *must ensure* that: • no other devices are mapped to the same memory addresses • shadow memory is not enabled at the same memory addresses • selection does not conflict with selection of BIOS EXT@D000 / D800 / E000 / E800
IRQ3 Source	← →	Determines source for IRQ3 interrupt. • Disabled • Serial J3 • Serial J4 (default) If set to disabled, IRQ3 may be an input from the PC/104 bus.
IRQ4 Source	← →	Determines source for IRQ4 interrupt. • Disabled • Serial J3 (default) • Serial J4 If set to disabled, IRQ4 may be an input from the PC/104 bus.
IRQ5 Source	← →	Determines source for IRQ5 interrupt. • Disabled (default) • Serial J3 • LPT If set to disabled, IRQ5 may be an input from the PC/104 bus.
IRQ7 Source	← →	Determines source for IRQ7 interrupt. • Disabled • LPT (default) • Serial J4 If set to disabled, IRQ7 may be an input from the PC/104 bus.

Shadow C000h-C7FFh Shadow C800-CFFFH Shadow D000-DFFFh	← →	Enables shadowing of the BIOS and memory. Selections are: • Enabled: address range is copied (shadowed) to RAM. • Disabled: address range remains mapped on the bus. In DOS systems, addresses between A0000H and FFFFFH are usually reserved for devices mapped on the bus. Accesses to these addresses are slower than accesses to system memory (RAM). The shadow options copy code from these addresses into RAM, improving general performance of the system.
Segment E000h Map	← →	Selects mapping of segment E000h of memory. Selections are: • PC/104 Bus • BIOS ROM When PC/104 Bus is selected, addresses in segment E0000-EFFFFh are free for external use. When BIOS ROM is selected, this segment is mapped into the on-board BIOS ROM chip.This selection will cause Setup to be executed at every boot, whether or not {Delete} is pressed.
Boot Type	← →	Selects boot type. Selections are: • Standard: Will perform RAM scan/checking • Quick: Will skip RAM scan/checking
Chipset Error	← →	Defines reaction to errors in microprocessor, coprocessor, timer, or DMA and interrupt controller initialization. ON: prints error warning OFF: continue without warning
Memory error	← →	Defines reaction to errors during memory tests. ON: prints error warning OFF: continue without warning This setting only applies during the following power-on tests: • memory size (base and extended) • memory test (base and extended)
Video Error	← →	Defines reaction to video initialization errors: ON: prints error warning OFF: continue without warning
Keyboard Error	← →	Defines reaction to keyboard initialization errors. ON: prints error warning OFF: continue without warning

Floppy Error	← →	Defines reaction to floppy drive errors. ON: prints error warning OFF: continue without warning
Hard Disk Error	← →	Defines reaction to hard disk errors. ON: prints error warning OFF: continue without warning
RTC Error	← →	Defines reaction to Real Time Clock initialization errors. ON: prints error warning OFF: continue without warning • When off is selected, the time and date default to 00:00:00 and 01/01/1990 in case of an error
Clock/Bus Speed	← →	• 33.3 (default for 100 or 133 MHz operation) • 25 • 20 • 15 • 10
<DEL> for Set-up	← →	Determines whether pressing the {Delete} key during boot will run the Setup program. • Enable • Disable • In some cases it may be desirable to disable this feature. • To re-enable the {Delete} key, insert JP5 and re-boot the cpuModule, then change this setting.

Save Changes and Exit

If you select this menu item, your changes are stored on the cpuModule. If you were running Setup from the BIOS ROM, the cpuModule automatically reboots. Changes will become effective the next time the cpuModule boots, as long as jumper JP5 is removed.

Exit Without Saving Changes

If you select this menu item, your changes are not stored on the cpuModule. If you were running Setup from the BIOS ROM, the cpuModule automatically reboots. Nothing in the cpuModule configuration will be changed, even after the reboot.

Read Settings from a File

If you select this menu item, you are prompted for a file which contains settings to be loaded. The settings will not be saved to the board unless you select Save Changes and Exit.

Save Settings to a File

If you select this menu item, you are prompted for the name of a file to which settings will be saved (a file name with extension). These settings may be moved to another cpuModule, or used to configure a number of cpuModules identically.

CHAPTER 5: USING THE CPUMODULE

This chapter provides information for users who wish to develop their own applications programs for the cpuModule.

This chapter includes information on the following topics:

- Memory map
- I/O Address map
- Interrupts
- Power On Self Tests (POSTs)
- System Functions (EEPROM, Watchdog Timer, Real Time Clock)
- Virtual Devices
- Storing Applications in Solid State Disk
- Utility Programs (SSD and BIOSBLD)

Memory Map

The module addresses memory using 24 address lines. This allows a maximum of 2^{24} locations, or 16 Megabytes of memory.

The table below shows how memory in the first megabyte is allocated in the system.

First Megabyte Memory Map	
FFFFFH-F0000H	BIOS in Flash EPROM
EFFFFH-E0000H	User memory space which normally contains the Setup program. The Advanced Setup screen allows this segment to be mapped into the BIOS ROM or onto the PC/104 bus.
DFFFFH-C0000H	User memory space. Usually, memory between C0000H and C7FFFH is used for the BIOS of add-on VGA video cards.
BFFFFH-A0000H	Normally used for video RAM as follows: CGA 0B8000H to 0BFFFFH EGA/VGA 0A0000H to 0AFFFFH Monochrome 0B0000H to 0B7FFFH
9FFFFH-00502H	DOS reserved memory area
00501H-00400H	BIOS data area
003FFH-00000H	Interrupt vector area

Memory beyond the first megabyte can be accessed in protected mode, by using EMS or a similar memory manager. See your OS or programming language references for information on memory managers.

Input/Output Address Map

As with all standard PC/104 boards, the Input/Output (I/O) space is addressed by 10 address lines (SA0-SA9). This allows 2^{10} or 1024 distinct I/O addresses. Any add-on modules you install must therefore use I/O addresses in the range 0-1024 (decimal) or 000-FFF (hex).

If you add any PC/104 modules or other peripherals to the system you must ensure they *do not* use reserved addresses listed below, or malfunctions will occur.

The table below lists I/O addresses reserved for the cpuModule.

I/O Addresses Reserved for the cpuModule		
Address Range	**Bytes**	**Device**
000H-00FH	16	DMA Controller
010H-01FH	16	Reserved for CPU
020H-021H	2	Interrupt Controller #1
022H-02FH	13	Reserved
040H-043H	4	Timer
060H-064H	5	Keyboard Interface
070H-071H	2	Real Time Clock port
080H-08FH	16	DMA page register
0A0H-0A1H	2	Interrupt controller #2
0C0H-0DFH	32	DMA controller #2
0F0H-0FFH	16	Math co-processor
1F0H-1FFH	16	Hard disk [1]
2F8H-2FFH	8	Serial port [2]
378H-37FH	8	Parallel port [3]
3BCH-3BFH	4	Parallel port [3]
3E8H-3EFH	8	Serial port [2]
3F0H-3F7H	8	Floppy disk [1]
3F8H-3FFH	8	Serial port [2]

[1] If the floppy and/or hard drive controllers are disabled, the I/O addresses listed will not be occupied.

[2] Only one of the I/O addresses shown for a Serial port is active at any time. You can use Setup to select which one is active or to disable it entirely.

[3] Only one of the I/O addresses shown for the Parallel printer port is active at any time. You can use Setup to select which one is active or to disable it entirely.

Hardware Interrupts

If you add any PC/104 modules or other peripherals to the system you must ensure they *do not* use interrupts needed by the cpuModule, or malfunctions will occur

The cpuModule supports the standard PC interrupts listed below. Interrupts not in use by hardware on the cpuModule itself are listed as 'available'.

Hardware Interrupts Used on the cpuModule		
Interrupt	**Normal Use**	**Source**
0	Timer 0	ACC chipset
1	Keyboard	ACC chipset
2	Cascade of IRQ 8-15	ACC chipset
3	COM2	ACC chipset
4	COM1	ACC chipset
5	available	XT bus
6	Floppy [1]	XT bus
7	Printer	ACC chipset
8	Real Time Clock	ACC chipset
9	available	XT bus
10	available	AT bus
11	available	AT bus
12	Not available	ACC chipset
14	IDE hard disk [2]	AT bus
15	available	ACC chipset

[1] Floppy disk interrupt, INT6, is available for use if no floppy disk is present in the system and floppy disk is disabled in Setup.

[2] Hard disk interrupt, INT14, is available for use if no hard disk drive is present in the system and hard disk is disabled in Setup.

The BIOS

The BIOS (Basic Input/Output System) is software that interfaces hardware-specific features of the cpuModule to an operating system (OS). Physically, the BIOS software is stored in a Flash EPROM on the cpuModule. Functions of the BIOS are divided into two parts:

The first part of the BIOS is known as POST (Power-On Self-Test) software, and it is active from the time power is applied until an OS boots (begins execution). POST software performs a series of hardware tests, sets up the machine as defined in Setup, and begins the boot of the OS;

The second part of the BIOS is known as the CORE BIOS. It is the normal interface between cpuModule hardware and the operating system which is in control. It is active from the time the OS boots until the cpuModule is turned off. The CORE BIOS provides the system with a series of software interrupts to control various hardware devices.

The following sections discuss the sections of the BIOS in more detail and describe features of the BIOS which may be useful to you in developing applications.

Power On Self Tests (POSTs)

When you turn on system power, the BIOS performs a series of tests and initializations. Each test or initialization step is identified by a numeric "POST" code written to I/O address 378H. These codes can be displayed using a commercially available "POST code display board". The following table lists the POST codes expressed in hexadecimal, with their corresponding meanings.

POST code list	
Code	**Meaning**
00H	CPU validation
01H	CPU test
02H	Component default programming
03H	Timer initialization
04H	Refresh line test
05H	BIOS EPROM test
06H	Keyboard controller test
07H	First 64K RAM test
08H	EEPROM test
09H	0F0000H-0FFFFFH shadow memory test
0AH	DMA and interrupt controller initializations
0BH	Video device test
0CH	Timer #2 test
0DH	DMA controller #1 test
0EH	DMA controller #2 test
0FH	DMA page control registers test
10H	Interrupt controller #1 test
11H	Interrupt controller #2 test
12H	Shutdown byte test
13H	Interrupt line 0 test
14H	Keyboard test
15H	Protected-mode switch test
16H	Base memory size
17H	Expanded memory size
18H	Base memory test
19H	Expanded memory test
1AH	Co-processor test
1BH	Real Time Clock test
1CH	IRQ line test
1DH	Parallel port test
1EH	Floppy disk test
1FH	Hard disk test
20H	Serial port test
21H	Mouse test
22H	Shadow RAM test

Errors While Booting

If an error occurs while the system is booting and performing the Power On Self Tests, the system will respond in one of several ways. Its response depends on what type of error occurred and on certain selections made in Setup.

Any error encountered in POST 1 through 7 causes the module to halt.

Errors encountered after POST 7 are dealt with according to settings made in Setup:

- With an error set to OFF in the Setup, a message is displayed on the screen and the speaker beeps. The boot continues if possible.
- With an error set to ON in the Setup, a message is displayed on the screen (if possible) and you are asked for confirmation before the boot continues.

If an error is detected in the EEPROM test (POST code 8) the system sets itself according to the default configuration presented in the following section. In that case, the system displays the detected errors and waits for confirmation before the boot continues.

When an error occurs and you are asked for confirmation to continue the boot, the {F1} key must be pressed to continue.

Default Configuration

In addition to the Setup configuration stored on the board, the cpuModule has a permanent default configuration. The system will resort to using this default configuration in two situations:

- An error occurs when accessing the EEPROM which holds the Setup on the module.
- You force use of the default configuration, as explained in the following section.

The default configuration is listed below.

BIOS Default Configuration	
Function	**Default selection**
Chipset error	on
Hard disk 1	not installed
Hard disk 2	not installed
Boot device	Atmel SSD, then Floppy
Floppy Drive 1	3.5" 1.44 Meg
Floppy Drive 2	not installed
Floppy Error	off
Hard disk Error	off
Serial port 1	3F8H
Serial port 2	disabled
Keyboard	AT
Keyboard Error	off
Memory Error	on
Memory Size	8 MB
Parallel Port	LPT1 at 378H
384K remap	disabled
Real Time Clock Error	off
Shadow options	disabled
SSD socket 1	2 MB DiskOnChip @ D000
SSD socket 2	none
SSD window	D0000H
Video State	EGA/VGA
VideoErr	off

Bypassing the Stored Configuration

Under certain circumstances, you may want to bypass the configuration stored on the board. To do this:

- Insert jumper JP5. This will force the cpuModule to boot using the default configuration.
- Press the {Delete} key to enter Setup.

You can then reconfigure the cpuModule correctly using Setup.

See ***Storing Applications On-board*** on page 74 for the locations and functions of jumpers.

BIOS Routines for Hardware Control

The cpuModule BIOS provides several routines which you may find useful to control hardware in your application programs. Because they control hardware which is specific to this cpuModule, these routines are also specific to this cpuModule.

Routines are provided for:

- EEPROM Control
- Watchdog Timer Control

The following sections describe these functions in detail.

EEPROM Control

The cpuModule is equipped with an EEPROM, or "Electrically Erasable and Programmable Read Only Memory". This part is primarily used to store the configuration from the Setup program. You can also use this part for non-volatile storage of a small amount of data. Its contents are retained even with system power off and no backup battery connected.

The EEPROM consists of 1024 bits organized as 64 words of sixteen bits each. Thirty-two words are used by the BIOS to store Setup information. The remaining 32 words are available to your applications. You may access these memory locations using functions of software interrupt 52H, which are listed below.

NOTE! The EEPROM will wear out after a large number of write cycles. You should *not* use the EEPROM to hold data which is updated frequently.

To prevent unintended changes to the Setup stored in the EEPROM, we recommend you always access the EEPROM using the interrupt functions listed below

Function 0	EEPROM write/erase enable. It is active until the next disable command and allows the device to be written and erased.
INPUTS:	AH = 0
RETURNS:	AH = error code
Function 1	EEPROM write/erase disable. This instruction must always be the last operation performed, to prevent undesired EEPROM access.
INPUTS:	AH = 1
RETURNS:	AH = error code
Function 2	EEPROM read. Reads from the device address specified in AL the number of words specified in CX, then stores the read values into the buffer addressed by ES:DI
INPUTS:	AH = 2 AL = address (0-3FH accepted) CX = number of words to read ES:DI = pointer to the buffer where the read values are stored
RETURNS:	AH = error code; if AH<>0, then AL = number of locations read
Function 3	EEPROM write. Writes at the device address specified in AL, for the number of words specified in CX, the values pointed by DS:SI. Does not allow write operations at locations 0 to 1FH, which are reserved**.**

INPUTS:	AH = 3 AL = word address (20H-3FH accepted) CX = number of words to read DS:SI = pointer to the buffer where the read values are stored
RETURNS:	AH = error code; if AH<>0, then AL = number of locations written
Function 4	EEPROM verify. Verifies that the values contained in the device at the address specified by AL, for the number of words specified in CX, match the values in the buffer pointed to by ES:DI
INPUTS:	AH = 4 AL = word address (0-3FH accepted) CX = number of words to read ES:DI = pointer to the buffer where the read values are stored
RETURNS:	AH=error code if AH = FF, then AL = address where the compare failed
Function 5	EEPROM Erase. Erases words, starting from the address specified in AL, for the length specified in CX
INPUTS:	AH = 5 AL = word address 20H-3FH accepted) CX = number of words to read
RETURNS:	AH = error code; if AH<> 0, then AL= number of locations erased
Error codes	Errors detected by interrupt 52H are returned in register AH with the following code:
register AH:	00H no errors 10H access attempted to locations reserved by the BIOS 20H invalid address 40H illegal command 80H time-out FFH error in verify procedure

When you perform simple EEPROM read operations, you do not need to enable the EEPROM and can use the BIOS read command (function 2) directly.

When you perform EEPROM write operations, you must perform a correct write cycle as follows:

- enable the EEPROM
- erase the relevant locations
- write the relevant locations
- disable the EEPROM
- verify that the write operation has been correctly performed

An example BASIC program illustrating EEPROM access is in the file CMV_EE.BAS on the cpu-Module utility disk.

Watchdog Timer Control

The cpuModule includes a Watchdog Timer, which provides protection against programs "hanging", or getting stuck in an execution loop where they cannot respond correctly. When enabled, the Watchdog Timer must be periodically reset by your application program. If it is not reset before the timeout period of 1.2 seconds expires, it will cause a reset of the cpuModule.

Three functions have been implemented on the cpuModule for Watchdog Timer control. These are:

- Watchdog Timer enable
- Watchdog Timer disable
- Watchdog Timer reset

You may control the watchdog timer using functions of software interrupt 52H listed below.

Function 0CH	Watchdog Timer enable
INPUTS:	AH = 0CH
RETURNS:	None
Function 0DH	Watchdog Timer disable
INPUTS:	AH = 0DH
RETURNS:	None
Function 0EH	Watchdog Timer reset
INPUTS:	AH = 0EH
RETURNS:	None

Direct Hardware Control

Some of the cpuModule hardware is controlled directly without using BIOS routines. These include:

- Real Time Clock Control
- Parallel Port Control

The following sections describe use of these features.

Real Time Clock Control

The cpuModule is equipped with a Real Time Clock (RTC) which provides system date and time functions, and also provides 64 non-volatile memory locations. The contents of these memory locations are retained whenever an external backup battery is connected, whether or not system power is connected. These locations are RAM, and do not wear out as the EEPROM locations do.

You may access the RTC date, time, and memory using an index and data register at I/O addresses 70h and 71h. Address 70h is the Index register. It must be written with the number of the register to read or write. Refer to the map below for valid choices for the index. Data is then written to or read from the selected register by writing or reading (respectively) the data register at address 71h.

Do *not* change values stored in the RTC registers listed as RESERVED in the table below. Doing so will interfere with proper cpuModule operation.

Registers of the Real Time Clock are shown below:.

Real Time Clock Registers			
Registers (hex)	**Registers (decimal)**	**Number of Bytes**	**Function**
00h	0	1	BCD Seconds
02h	2	1	BCD Minutes
04h	4	1	BCD Hours
06h	6	1	Day of week
07h	7	1	Day of month
08h	8	1	Month
09h	9	1	Year
0A-31h	10-49	40	**RESERVED- Do not modify!**
32h	50	1	BCD Century
33-3Fh	51-63	13	**RESERVED - Do not modify!**
40-7Fh	64-127	64	User RAM

RTC access is illustrated in the following QuickBasic program fragment:

```
input "Enter address to write:", i%
input "Enter value to write:", j%
output &h70, i%
output &h71, j%

output &h70,i%
j% = input (&h71)
print "Read back value ";i%;" at address ";j%
```

Parallel Port Control

The parallel port may be operated in SPP (output-only) and bidirectional modes. The mode may be selected in Setup, or by application software.

An example BASIC program illustrating control and access to the parallel port is in file CMV_PAR.BAS on the utility disk.

Processor Clock Control

The processor clock can be programmed in the setup program. Further, the processor clock may be changed by a solder jumper on the back of the board. For 586DX133 boards, the switch is between clock-quadrupled and clock-tripled operation. For 486DX100 boards, the switch is between clock-tripled and clock-doubled operation. Please contact the factory for further information on implementing this change.

Please see ***Power Consumption*** on page 11 for a listing of Power Consumptions at different clock speeds.

Storing Applications On-board

The cpuModule was designed to be used in embedded computing applications. In these applications, magnetic media like hard disks and floppy disks are not very desirable. It is better to eliminate magnetic storage devices and place your operating system and application software into the cpuModule's Solid State Disk (SSD).

The following section describes two distinctly different ways you may use the Solid State Disk sockets of the cpuModule. These methods allows you to use a wide variety of memory devices to implement on-board Solid State Disk storage, each with its advantages and disadvantages.

Ways to Use the Solid State Disk Sockets

There are two ways you may utilize the Solid State Disk sockets of the cpuModule.

- Using devices which install as BIOS Extensions
- Using Conventional SSD Memory

BIOS Extension Devices such as Disk On Chip and PromDisk provide a relatively large amount of read/write disk space in one socket of the cpuModule. These devices generally appear similar to a conventional hard disk to DOS, allowing you to copy, delete, and rename files without using any special utilities.

Conventional Solid State Disk uses a variety of memory devices, such as:

- Atmel 5 volt only Flash
- Intel 12 volt Flash
- AMD 5-volt Flash
- Static RAM
- NOVRAM
- EPROM

to create a Solid State Disk. When used with Atmel 5 volt Flash, SRAM, or NOVRAM, the SSD appears similar to a read/write floppy disk to DOS, allowing you to copy, delete, and rename files in the SSD without using any special utilities.

When used with Intel 12 volt Flash or AMD 5-volt Flash, you can erase and program the SSD memory in the cpuModule using the SSD.EXE utility program.

These methods are described in detail in the following sections.

BIOS Extension Devices

You can use BIOS Extension Devices like M-Systems Disk On Chip and MCSI PromDisk to implement a Solid State Disk which can be read and written using normal disk commands.

Advantages of using these devices include:

- Storage capacity up to 72MB per socket (more in the future)
- Full read/write capability using standard OS file commands
- Integrated support for the QNX operating system is possible (contact M-Systems for information)

Disadvantages of using them include:

- Relatively high cost
- Current vendor software may allow only one device per cpuModule

Parts supported by the cpuModule include:

- M-Systems 2000 series: MD2200-D72 (72MB) down to...
- M-Systems 2000 series: MD2200-D02 (2MB)
- Optional QNX versions of the above parts

- M-Systems 1000 series: ED1202-D02 (2MB)
- M-Systems 1000 series: ED1202-D01 (1MB)

- MCSI PromDisk: 72300 (4MB)
- MCSI PromDisk: 72301 (8MB)

Our website at www.rtdusa.com provides links to the websites of these manufacturers.

Installing BIOS Extension Devices

To install these devices, follow this procedure:

- Apply power to the cpuModule and run Setup.

NOTE!	If you are using *both* a BIOS extension device and Conventional SSD in a cpuModule, the Conventional SSD *must* be placed in the first SSD socket.

- If you are using only a BIOS Extension Device, and no Conventional SSD, set **Solid State Disk** to **Disabled** in the Standard Setup screen.
- If you are using both a BIOS Extension Device and a Conventional SSD, set **Solid State Disk** to **Enabled** in the Standard Setup screen.
- If you are using the BIOS Extension Device in socket U9, set **SSD Device in U9** to an appropriate memory window.
- If you are using the BIOS Extension Device in socket U10, set **SSD Device in U10** to an appropriate memory window.
- If you are using the BIOS Extension Device in socket U1, set **SSD Device in U1** to an appropriate memory window.

• If you are using the BIOS Extension Device in socket U2, set **SSD Device in U2** to an appropriate memory window.

NOTE! The memory window selected for a BIOS extension device must not be used by any other program or hardware device. Make sure this window is not used by EMM386 or another memory manager, SSD, Ethernet card, PCMCIA card, etc.

If either SSD Device is:	SSD Window cannot be:
BIOS EXT @D000	D000
BIOS EXT @D800	D800
BIOS EXT @E000	E000
BIOS EXT @E800	E800

• Save your changes and exit Setup.

• Turn off the cpuModule.

• Set jumpers JP2 and JP3 or JP4 and JP5JP1 and JP2 or JP3 and JP4 to appropriate settings.
Please see ***SSD Jumpers*** on page 96.

• Install the BIOS Extension Device into the correct socket.

• Reboot the cpuModule. The BIOS Extension Device should appear as the next available hard drive in your system. If there is no other hard drive installed, it will appear as drive C:.

• Format the new drive using the DOS format command.

NOTE! If you wish to make the drive bootable, you must format it using the **/s** switch of the format command. Refer to your OS manual for more information.

• If you wish to boot from the BIOS Extension Device, run Setup and disable any other hard drive. Set the boot device to Hard Drive. The cpuModule will not boot to a BIOS Extension Device if another hard drive is enabled.

Conventional Solid State Disk

You can use numerous memory types to implement a Conventional Solid State Disk. Depending on the devices used, you may implement read/write, read-only, or write-once-read-many type drives.

Advantages of using the Conventional SSD include:

- Storage capacity up to 2MB total (EPROM only)
- Allows mixing of device types
- Atmel Flash allows read/write capability using standard DOS file commands

Disadvantages of using the Conventional SSD include:

- Requires external utility program to program 12 volt Flash, AMD 5-volt Flash, or EPROM.

The following memory devices or their equivalents may be used for a Conventional SSD. Access times for all devices must be 150 ns or less, and all devices *must* be in 32-pin DIP packages.

- Atmel 29C010A or 29C040A
- Intel 28F010 or 28F020
- AMD 29F010, 29F040
- SRAM 128Kx8, 512Kx8
- NOVRAM (Dallas Semiconductor DS1645Y, DS1650Y)
- EPROM (27C010, 27C020, 27C040, 27C080)

NOTE! There are two restrictions on mixing memory devices for a Conventional SSD:

If you use two SRAMs or two NOVRAMs, both devices must be the same size.

The first SSD socket must be filled before the second socket is used.

Installing a Conventional SSD using Atmel 5-volt-only Flash

To install an SSD using Atmel Flash, follow this procedure:

- Apply power to the cpuModule and run Setup.
- If you are using socket U9, set **SSD Device in U9** to the appropriate Atmel device type.
- If you are using socket U10, set **SSD Device in U10** to the appropriate Atmel device type.
- If you are using the device in socket U1, set **SSD Device in U1** to the appropriate device type.
- If you are using the device in socket U2, set **SSD Device in U2** to the appropriate device type.
- Set **SSD Window** to a value which will not conflict with other hardware or software.

NOTE! The memory window selected for DOC must not be used by any other program or hardware device. Make sure this window is not in use by EMM386 or another memory manager, or an SSD, Ethernet card, PCMCIA card, etc.

- Save your changes and exit Setup.
- Turn off the cpuModule.

- Set jumpers JP2 and JP3 or JP4 and JP5JP1 and JP2 or JP3 and JP4 to the appropriate settings. Please see ***SSD Jumpers*** on page 96.
- Install the memory device(s) into the correct socket(s).
- Reboot the cpuModule. The SSD should appear as the next available drive in your system.
- Format the SSD using the DOS format command.

NOTE! If you wish to make the SSD bootable, you must format it using the /s switch of the format command. Refer to your DOS manual for more information on format.

When using the MS-DOS format command, always specify a size parameter. Use a size larger than the installed SSD, e.g.

format /f:1.44M (for 2 x 512K Atmel Flash devices)

- If you wish to boot from the SSD, run Setup again and set the boot device to SSD.

Installing a Conventional SSD using Intel 12-volt Flash or AMD 5-volt Flash

Intel 12-volt Flash EPROMs and AMD 5-volt Flash can be programmed either directly on the cpuModule or externally. If you wish to program Flash EPROMs externally, follow the steps listed for programming EPROMs. Otherwise, follow the steps below.

To program these Flash EPROMs on-board, the procedure is:

- Apply power to the cpuModule and run Setup.
- If you are using socket U9, set **SSD Device in U9** to the appropriate device type.
- If you are using socket U10, set **SSD Device in U10** to the appropriate device type.
- If you are using the device in socket U1, set **SSD Device in U1** to the appropriate device type.
- If you are using the device in socket U2, set **SSD Device in U2** to the appropriate device type.
- Set **SSD Window** to a value which will not conflict with other hardware or software.

NOTE! The memory window selected for DOC must not be used by any other program or hardware device. Make sure this window is not in use by EMM386 or another memory manager, or an SSD, Ethernet card, PCMCIA card, etc.

- Save your changes and exit Setup.
- Turn off the cpuModule.
- Set jumpers JP2 and JP3 or JP4 and JP5JP1 and JP2 or JP3 and JP4 to the appropriate settings.
  Please see ***SSD Jumpers*** on page 96.
- Install the memory device(s) into the correct socket(s).

- On the cpuModule or another computer, format a floppy disk and copy onto it the files you wish to copy to the SSD. If you wish to boot from the SSD, you must format with the '/s' switch to copy system files. See your DOS manual for details of the format command.

NOTE! Start with a blank, newly-formatted disk each time you transfer files. You must copy files to the disk only one time, and must not delete, re-copy, or rename files on the floppy disk. If the files become fragmented, the process will not work!

- Apply power to the cpuModule.
- Connect programming voltage, Vpp, of 12Vdc (+/- 5%) to pin 10 of the Multifunction connector.
- Set jumper JP3 and/or JP5JP2 and/or JP4 to the required position to provide programming voltage (Vpp) to the Flash EPROMs.
  Please see page ***SSD Jumpers*** on page 96.
- Run the SSD program on the cpuModule. Perform the menu selections appropriate for the chosen memory devices, then start programming.
- When programming is complete, remove programming voltage by re-positioning jumpers JP3 and/or JP5JP2 and/or JP4.

After re-booting, the Solid State Disk will be seen by the system as a write-protected floppy. DOS commands normally used to read floppy disks will work with the SSD.

Installing a Conventional SSD using SRAM or NOVRAM

When the Solid State Disk is composed of SRAMs or NOVRAMs, it appears as a read/write disk and may be read and written using normal DOS disk commands.

To install an SRAM or NOVRAM SSD, you should follow this procedure:

- Apply power to the cpuModule and run Setup.
- If you are using socket U9, set **SSD Device in U9** to the appropriate SRAM or NOVRAM device type.
- If you are using socket U10, set **SSD Device in U10** to the appropriate SRAM or NOVRAM device type.
- If you are using the device in socket U1, set **SSD Device in U1** to the appropriate device type.
- If you are using the device in socket U2, set **SSD Device in U2** to the appropriate device type.
- Set **SSD Window** to a value which will not conflict with other hardware or software.

NOTE! The memory window selected for DOC must not be used by any other program or hardware device. Make sure this window is not in use by EMM386 or another memory manager, or an SSD, Ethernet card, PCMCIA card, etc.

- Save your changes and exit Setup.
- Turn off the cpuModule.

- Set jumpers JP2 and JP3 or JP4 and JP5 JP1 and JP2 or JP3 and JP4 to the appropriate settings. Please see page ***SSD Jumpers*** on page 96.
- Install the memory device(s) into the correct cpuModule socket(s).
- Reboot the cpuModule. The SSD should appear as the next available drive in your system.
- Format the SSD using the DOS format command.

If you wish to make the SSD bootable, you must format it using the /s switch of the format command. Refer to your DOS manual for more information on the format command.

If you wish to boot from the SSD, run Setup again and set the boot device to SSD.

Notes on Formatting an SRAM or NOVRAM SSD

For most purposes, you can format the SRAM or NOVRAM SSD as you would a 1.44MB floppy, using a command line similar to:

format b: /u

To get the most possible space in the disk and ensure proper operation, use the format command with a size parameter just over the total size of the installed SSD memory. For example, if you install 256Kbytes of SRAM, you should use format with the parameters for a 360Kbyte floppy disk. For example:

ROM-DOS:*format b: /u /n:9 /t:40*

MS-DOS:*format b: /f:360K*

See your DOS manual for details on the format command and its parameters.

Installing a Conventional SSD using EPROM

EPROMs for an SSD must be programmed externally to the cpuModule, using an EPROM programmer and following the procedure below.

To install an EPROM SSD, you should follow this procedure:

- Apply power to the cpuModule and run Setup.
- If you are using socket U9, set **SSD Device in U9** to the appropriate EPROM device type.
- If you are using socket U10, set **SSD Device in U10** to the appropriate EPROM device type.
- If you are using the device in socket U1, set **SSD Device in U1** to the appropriate device type.
- If you are using the device in socket U2, set **SSD Device in U2** to the appropriate device type.
- Set **SSD Window** to a value which will not conflict with other hardware or software.

NOTE!	The memory window selected for DOC must not be used by any other program or hardware device. Make sure this window is not in use by EMM386 or another memory manager, or an SSD, Ethernet card, PCMCIA card, etc.

- Save your changes and exit Setup.

- On the cpuModule or another computer, format a floppy disk and copy onto it the files you wish to copy to the SSD. If you wish to boot from the SSD, you must format with the '/s' switch to copy system files. See your DOS manual for details of the format command.

NOTE!	Start with a blank, newly-formatted disk each time you transfer files. You must copy files to the disk only one time, and must not delete, re-copy, or rename files on the floppy disk.

- Boot the cpuModule and start the SSD program. Select settings appropriate for the chosen EPROMs.
- Select the Binary File "construct" option and then Start execution; the program will create an EPROMx.BIN file for each EPROM.
- Use the EPROMx.BIN file created to program EPROMs with an appropriate EPROM programmer.
- With the cpuModule off, set jumpers JP2 and JP3 or JP4 and JP5JP1 and JP2 or JP3 and JP4 to the appropriate settings for the EPROM you are using. Please see ***SSD Jumpers*** on page 96.
- Boot the cpuModule.

After booting, the Solid State Disk will be seen by the system as a write-protected floppy. DOS commands normally used to read floppy disks will work with the SSD.

Directly Accessing the Solid State Disk

If you wish to directly access the Solid State Disk of the cpuModule, you may do so using an extension to interrupt 52H.

Contact the factory for additional information on doing so.

Using Virtual Devices

The cpuModule is designed for use in industrial environments as a stand-alone module, without external peripherals. Nevertheless, it may be necessary to interface a cpuModule with I/O devices like a keyboard, monitor, or floppy or hard drive, especially for set-up or maintenance.

The cpuModule is therefore provided with “Virtual Devices”, which allows you to access a keyboard, monitor, and floppy disks without directly connecting them to the PC/104 bus of the module. Instead, the cpuModule serial port is connected to the serial port of a PC or AT “host” computer. The host computer’s keyboard, monitor, and floppy disks can then be made available to the cpuModule. You can then boot from the host’s floppy drives, edit and debug programs using the host’s keyboard and monitor, and so on.

NOTE! Virtual Devices mode is intended for use during development, testing, and servicing of the cpuModule. It is *not* intended for use during normal operation of the cpuModule. The overhead required by Virtual Devices will probably cause unacceptable performance while running an application.

If you require user I/O through the serial port, we strongly recommend you implement your own serial I/O or use a commercial software product intended for this purpose.

There are two limitations when using Virtual Device mode:

- programs must operate only in text mode
- program screen input/output must use only BIOS calls

Applications which use graphics modes or directly access hardware (video memory, the keyboard, or the disk drives) will not work properly.

To use Virtual Devices mode, you will need:

- a PC or AT compatible “host” computer with a serial port
- the connection program (SERRX.EXE) available on the host computer
- a "null-modem" cable with the transmit data, receive data, and ground pins connected
- the cpuModule

There are two ways to initiate Virtual Device mode. You can enable the mode by using the cpuModule Setup program, or by jumpering pins on the first serial port connector of the cpuModule. Please note that behavior differs slightly depending on how Virtual Device mode is initiated. The following sections discuss the two methods.

Initiating Virtual Devices from Setup

If the cpuModule is operational, Virtual Device mode can be accessed from Setup. This method has the advantage that you can individually select devices for use in Virtual Devices mode. To use this method, run Setup on the cpuModule and select the Virtual Devices you wish to use. The settings for floppy drive A:, keyboard, and video state, and hard disk C: can each be set to "serial". Save your changes and then follow the procedure below:

1) Turn off power to the cpuModule system.
2) Connect the null modem cable between the cpuModule and host computer.
3) Turn on the host computer.
4) Start the SERRX.EXE program on the host computer, specifying which serial port of the host computer you wish to use.
5) Turn on the cpuModule system.

The cpuModule system will now boot from the disk drive you configured in Setup. If you have a C: disk on the PC/104 system, it will be drive D:.

Initiating Virtual Devices by Jumpering Serial Port Pins

Virtual Device mode can also be initiated by shorting two pins on the first or second serial port connector of the cpuModule. This method has a slight disadvantage in that the keyboard, video, and floppy and hard drives are all redirected to the serial port. To use this method, you must short (connect) two pins on the first serial port connector. The exact procedure is:

- Turn off power to the cpuModule system.
- Carefully connect the RI and DTR pins (7 and 8) of the serial port connector (refer to the chapter on Connecting the cpuModule for pin locations).
- Connect the null modem cable between the cpuModule and the host computer.
- Turn on the host computer.
- Start the SERRX.EXE program on the host computer, specifying which serial port of the host computer you wish to use.
- Turn on the cpuModule system.

The cpuModule system will then boot from the host computer’s disk drives. The drive it boots from will be the one selected in Setup. Note that if both the PC/104 system and the host computer have C: disks, the one on the host computer's remains disk C:, while the one on the cpuModule becomes available as drive D:.

Disconnecting the Host Computer

To disconnect the host computer, press the {Prt Scrn} key at any time. The host computer will recover its peripherals and returns to normal operation.

To re-connect the cpuModule to the host, re-run SERRX.EXE on the host and wait for the message:

Waiting .....

and then press the {Return} or {Enter} key.

Notes when Using Virtual Device Mode

You will find it useful to remember the following points when using Virtual Devices:

Large data transfers (file accesses, display updates, etc.) take considerable time in Virtual Device mode. Please be patient.

When you make the keyboard a Virtual Device, the key combination CTRL-ALT-DEL is not passed to the cpuModule; it resets the host computer instead.

When you make floppy drive A: a Virtual Device, both A: and B: floppy disks are actually redirected to the host computer.

If a communication error occurs on the serial port link, you will hear a beep from both the host computer and the cpuModule (assuming speakers are present in both systems).

Utility Programs

The cpuModule is supplied with several utility programs needed for programming a Conventional SSD or reprogramming the BIOS. The following sections discuss these utilities in detail.

Solid State Disk Utility (SSD.EXE)

The Solid State Disk utility program (SSD.EXE) allows you to program applications into 12 volt Flash or conventional EPROMs for use in a Conventional Solid State Disk. It is supplied on the cpu-Module utility floppy disk. Use of the program is described below.

Available Options

The SSD program screen is divided into two areas:

- the upper part contains user-selectable fields
- the lower part contains help messages and displays program output

Once you make selections, you can:

- start executing the program, by pressing the {S} key
- quit the program, by pressing the {Q} key.

Field Selection

You can make selections using the keys listed in the following table.

SSD Active Keys	
Key	**Function**
↓	selects next field
↑	selects previous field
{TAB}	selects next field to the right or first field of next line
←	selects next value in field
→	selects previous value in field

Contents of the Fields

The following is a list of selectable fields in the SSD program:

Selectable Fields		
Field	**Active keys**	**Selections**
Binary Files	← →	Enables creation of binary files (EPROMx.BIN) needed to program EPROMs for the Solid State Disk. Selections: • Construct • None The program creates the .bin files in the directory from which it is run. When working with a single floppy **do not** enable the Construct option.

Devices Dimension	← →	Selects the size of each memory device for the SSD. Possible selections: • Flash (128k, 256k) • EPROM (128k, 256k, 512k, 1Mbyte) • RAM (128k, 512k) Select a setting which agrees with the installed memory devices and the positions of jumpers JP1, JP2, JP3, and JP4.
Devices Number	← →	Selects the number of memory devices for the SSD. Possible selections: • One • Two
Devices Type	← →	Selects the type of memory devices used to implement the Solid State Disk. Possible selections: • Flash • EPROM If EPROM is selected, the binary files *construct* mode is automatically enabled.
Input File	← → {TAB},{char}	Defines the name of the input file in MiniDOS or BIOS Extension mode. In MiniDOS mode, the filename must have the extension .EXE.
MiniDOS option	← →	Selects either MiniDOS or BIOS Extension mode.
Source Disk	← →	Selects the floppy you wish to have copied into the SSD.
SSD Window	← →	Selects the memory window used for the SSD. Selections are • from 0C0000H • to 0EC000H by 16Kbyte steps. This window is used only when programming the SSD in the cpuModule socket(s). It must not be in use by any other device.

BIOS Build Utility (BIOSBLD.EXE)

The BIOS Build utility program, BIOSBLD.EXE, allows you to re-program the BIOS.

Incorrectly programming the BIOS can completely halt operation of the cpuModule, requiring it to be returned to the factory. Do not attempt to reprogram the BIOS unless you fully understand the procedure.

BIOS Organization

The cpuModule BIOS is in a 128k byte Flash EPROM. The ROM is at addresses E0000H through FFFFFH.

The first 64kbytes, from E0000H to EFFFFH, contains the Setup program executed when the {Delete} key is held during boot. The upper 64kbytes, from F0000H to FFFFFH, contains the normal PC BIOS of the cpuModule.

Using BIOSBLD

The program is run by entering the following command line:

BIOSBLD <file_name> /<start_address>

Where:

<file_name>: Name of the file to be programmed into the Flash EPROM.

<start_address>:Selects the starting address for programming. Selections are:

- **/E0000** to start at address E0000H
- **/F0000** to start at address F0000H

Use /E0000 if reprogramming with a 128 KB BIOS file, or /F0000 if reprogramming with a 64KB BIOS file.

Example:

To reprogram the BIOS with the file MYROM.400 (which is 128KB long), you would use the command line:

biosbld myrom.400 /E0000

NOTE!	To program the BIOS, you must apply a programming voltage, Vpp, to the Multifunction connector. This voltage must be present during the entire execution of the BIOSBLD.EXE program. Refer to the Multifunction connector description for details on connecting Vpp. The BIOSBLD program ends by resetting the cpuModule.

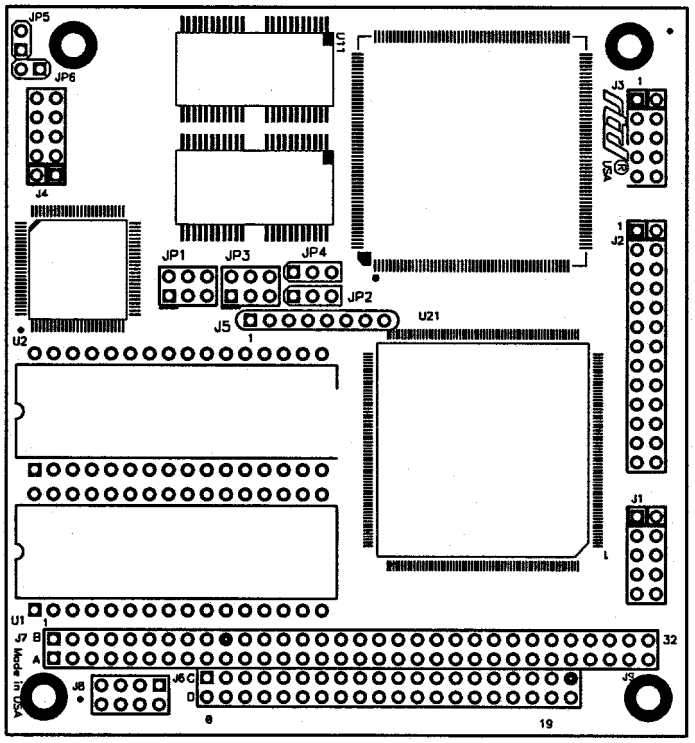
CHAPTER 6: HARDWARE REFERENCE

This appendix gives information on the cpuModule hardware, including:

- jumper settings and locations
- solder jumper settings and locations
- mechanical dimensions
- processor thermal management

Jumpers

The figure below shows the locations of the jumpers used to configure the cpuModule. To use the figure, position the module with the PC/104 bus connector at the six o'clock position and the component side facing up.The table below lists the jumpers and their settings.



Jumper	Use
JP 1	6-pin jumper. Used with JP2 to configure first SSD socket. Factory Default: no battery backup (position 1-2)
JP 2	3-pin jumper Used with JP1 to configure first SSD socket. Factory Default: selects Atmel 512K Flash memory (position 1-2)
JP 3	6-pin jumper Used with JP4 to configure second SSD socket. Factory Default: no battery backup (position 1-2)
JP 4	3-pin jumper Used with JP3 to configure second SSD socket. Factory Default: selects Atmel 512K Flash (position 1-2)

JP 5	2-pin jumper Open: Use Setup stored on board; boot normally Closed: Use default Setup Factory Default: Closed
JP 6	2-pin jumper RESERVED. Do not close. Factory Default: Open

SSD Jumpers

For convenience, tables for the selection of SSD type and size have been repeated below.

The following table lists the possible configurations for the first socket of the SSD and the corresponding jumpers which must be set:

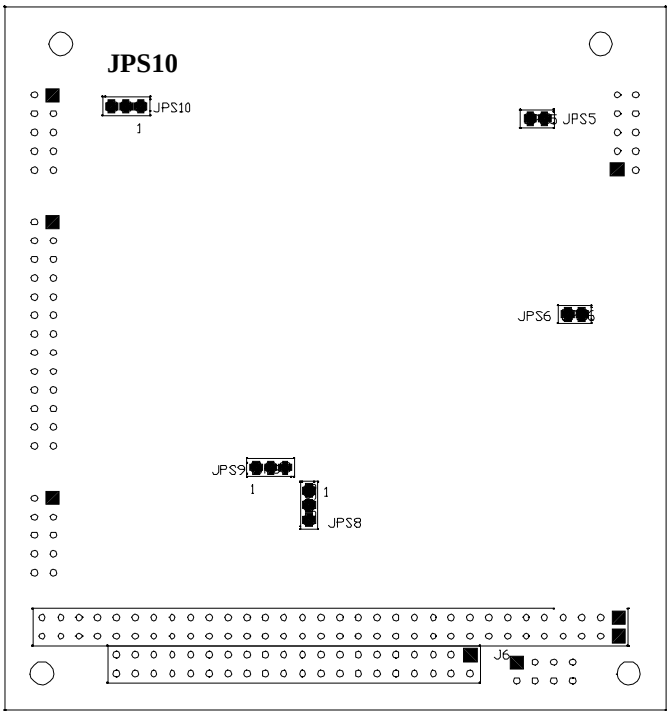
Jumpers for First SSD Socket, U1						
Type	**Part**	**Operation**	**Capacity**	**JP1**	**JP2**	**Notes**
Atmel 5V Flash	29C010A	read/write	128KB	1-2	1-2	
	29C040A	read/write	512KB	1-2	1-2	
BIOS Extension Devices	DiskOnChip and PromDisk	read/write	to 12MB+	3-4	1-2	
NOVRAM	DS1645Y	read/write	128KB	3-4	1-2	
	DS1650Y	read/write	512KB	1-2	1-2	
SRAM	128KB	read/write	128KB	3-4	1-2	no backup
				3-4	2-3	battery backup
	512KB	read/write	512KB	1-2	1-2	no backup
				1-2	2-3	battery backup
12V Flash	28F010	read-only	128KB	5-6	1-2	programming
				3-4	1-2	read-only
	28F020	read-only	256KB	5-6	1-2	programming
				3-4	1-2	read-only
AMD 5V Flash	29F010	read-only	128KB	1-2	1-2	program or read
	29F040	read-only	512KB	1-2	1-2	program or read
EPROM	27C010	read-only	128KB	3-4	1-2	
	27C020	read-only	256KB	3-4	1-2	
	27C040	read-only	512KB	3-4	1-2	
	27C080	read-only	1MB	1-2	1-2	

The following table lists the possible configurations for the second socket of the SSD and the corresponding jumpers which must be set:

Jumpers for Second SSD Socket, U2						
Type	**Part**	**Operation**	**Capacity**	**JP3**	**JP4**	**Notes**
Atmel 5V Flash	29C010A	read/write	128KB	1-2	1-2	
	29C040A	read/write	512KB	1-2	1-2	
BIOS Extension Devices	DiskOnChip and PromDisk	read/write	to 12MB+	3-4	1-2	
NOVRAM	DS1645Y	read/write	128KB	3-4	1-2	
	DS1650Y	read/write	512KB	1-2	1-2	
SRAM	128KB	read/write	128KB	3-4	1-2	no backup
				3-4	2-3	battery backup
	512KB	read/write	512KB	1-2	1-2	no backup
				1-2	2-3	battery backup
12V Flash	28F010	read-only	128KB	5-6	1-2	programming
				3-4	1-2	read-only
	28F020	read-only	256KB	5-6	1-2	programming
				3-4	1-2	read-only
AMD 5V Flash	29F010	read-only	128KB	1-2	1-2	program or read
	29F040	read-only	512KB	1-2	1-2	program or read
EPROM	27C010	read-only	128KB	3-4	1-2	
	27C020	read-only	256KB	3-4	1-2	
	27C040	read-only	512KB	3-4	1-2	
	27C080	read-only	1MB	1-2	1-2	

Solder Jumpers

Solder jumpers are set at the factory and normally you will not need to change them. All solder jumpers are located on the module's solder side. The diagram below shows the locations of the solder jumpers. To use the diagram, position the module with the PC/104 bus connector at the six o'clock position and the solder side facing up..

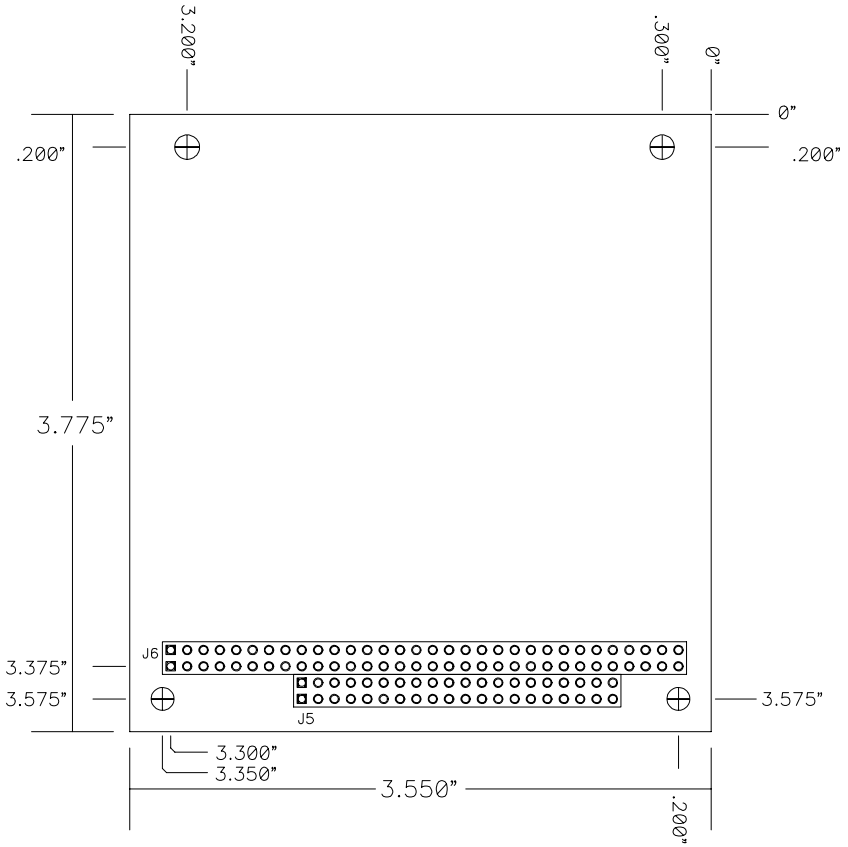


The following table lists the solder jumpers and their settings.

JPS 5	2-pad jumper Reserved for factory use. Leave closed.
JPS 6	2-pad jumper Reserved for factory use. Leave closed.
JPS8	3-pad jumper Reserved for factory use. Leave as set.
JPS9	3-pad jumper Reserved for factory use. Leave as set.
JPS 10	3-pad jumper Selects clock-multiplier for processor. For 5x86DX133: 1-2: clock-quadrupled 2-3: clock-tripled For 486DX100: 1-2: clock-doubled 2-3: clock-tripled Defaults: 1-2 for 5x86DX133; 2-3 for 486DX100

Mechanical Dimensions

The following figure shows mechanical dimensions of the module (in inches).



Mechanical Dimensions (+/- 0.005")

486DX100/66 Processor Thermal Management

The industrial grade processor IC of the cpuModule must receive adequate cooling to ensure proper operation and good reliability. The processor is therefore supplied with an attached heatsink.

NOTE!	This cpuModule is *not* warranted against damage caused by overheating due to improper or insufficient heatsinking or airflow.

The table below shows the maximum ambient temperature allowed.

Maximum Allowable Ambient Temperature	
Without heat sink	70 C
With heat sink	86 C
With heat sink and fan	98 C

Values shown are valid for all possible clock frequencies.

5x86DX133 Processor Thermal Management

The processor IC of the cpuModule must receive adequate cooling to ensure proper operation and good reliability. The processor is therefore supplied with an attached heatsink.

NOTE!	This cpuModule is *not* warranted against damage caused by overheating due to improper or insufficient heatsinking or airflow.

The table below shows the maximum ambient temperature allowed at various airflows while preventing damage to the processor.

Maximum Allowable Ambient Temperature	
Without heat sink	45 C
With heat sink	66 C
With heat sink and fan	82 C

Values shown are valid for all possible clock frequencies.

CHAPTER 7: TROUBLESHOOTING

Many problems you may encounter with operation of your cpuModule are due to common errors. This chapter will help you get your system operating properly.

It contains:

- Common problems and solutions
- Troubleshooting a PC/104 system
- How to obtain technical support
- How to return a product

Common Problems and Solutions

The following table lists some of the common problems you may encounter while using your cpuModule, and suggests possible solutions.

If you are having problems with your cpuModule, please review this table *before* contacting technical support.

Problem	Cause	Solution
cpuModule "will not boot"	no power or wrong polarity	check for correct power on PC/104 bus connectors
	incorrect Setup (video disabled, etc.)	install jumper JP5; reboot and press {Delete} key to run Setup
	defective or mis-connected device on bus	check for misaligned bus connectors; remove other cards from stack
	cable connected backwards	verify all cables are connected correctly
	SSD installed backwards	check for an SSD memory installed in socket backwards
	entering Virtual Devices mode	check if first or second serial port is jumpered to force Virtual Devices mode
does not recognize Setup changes	jumper JP5 installed	turn off power, remove JP5, reboot
Setup always runs at boot, whether or not {Delete} key is held	E000 segment mapped to BIOS ROM	Enter Advanced Setup screen, change E000 Segment Map to 'PC/104 Bus'
will not boot from particular drive or device	device not bootable	use sys command on drive or re-format the device using the **/s** switch
	device not formatted	format drive using **/s** switch
	power not connected to boot drive	connect power cable to floppy or hard drive
"General Failure..." message attempting to access Atmel Flash in SSD	jumpers incorrectly set	set SSD jumpers correctly; see Jumper Setting tables for SSD; Note: if device was formatted with jumpers set incorrectly, it *must* be re-formatted
Added second Atmel Flash to SSD; will not re-format to larger size	format command must have size specified	execute format command with **/f:1.44** switch
Atmel Flash shows disk space available, but it cannot be written	part smaller than 1.44MB was formatted as 1.44MB; it will show space available even when full	ignore "disk space remaining" messages from DOS REMEMBER! A bootable disk contains 3 hidden files plus format info, totalling about 150kB

will not boot from DiskOnChip	DiskOnChip is not the only hard drive in system	disable other hard drive(s) in system
	using wrong DiskOnChip device (not 32 pin)	change to correct (32 pin) DiskOnChip
	Boot device not set to Hard disk	run Setup and set boot device to Hard Drive
erratic operation	excessive bus loading	reduce number of PC/104 modules in stack; remove termination components from bus signals; remove Tri-M power supply bus terminations
	power supply noise	examine power supply output with oscilloscope; glitches below 4.75Vdc will trigger a reset; add bypass caps
	power supply limiting	examine power supply output with oscilloscope; check for voltage drop below 4.75V when hard drive or floppy drive starts; add bypass caps
	temperature too high	add fan, processor heatsink, or other cooling device(s) See ***486DX100/66 Processor Thermal Management*** on page 100.
	memory address conflict	check for two hardware devices (e.g. Ethernet, SSD, Arcnet, PCMCIA) trying to use the same memory address check for two software devices (e.g. EMM386, PCMCIA drivers, etc.) trying to use the same memory addresses check for hardware and software devices trying to use the same memory address check for an address range shadowed (see Advanced Setup screen) while in use by another hardware or software device
	I/O address conflict	check for another module trying to use I/O addresses reserved for the cpuModule between 010h and 020h check for two modules (e.g. dataModules, PCMCIA cards, Ethernet) trying to use the same I/O addresses
Will not enter Virtual Devices mode	correct pins not jumpered	jumper pins 7&8 (RI and DTR) of first or second serial port

	incorrect cable	cable must 'criss-cross' TXD and RXD lines from end to end
keyboard does not work	keyboard interface damaged by misconnection	check if keyboard LEDs light
	wrong keyboard type	verify keyboard is an 'AT' type or switch to 'AT' mode
Windows 3.1x installation program hangs	smartdrive enabled	remove smartdrive command from config.sys, reboot, run install program
floppy drive light always on	cable misconnected	check for floppy drive cable connected backwards
two hard drives will not work, but one does	both drives configured for master	set one drive for master and the other for slave operation (consult drive documentation)
floppy does not work	"data error" due to drive upside down	orient drive properly (upright or on its side)
will not boot when video card is removed	illegal calls to video controller	look for software trying to access non-existent video controller for video, sound, or beep commands
won't boot from PCMCIA hard drive	booting from PCMCIA is not supported	boot from SSD, use autoexec.bat to load PCMCIA drivers, run application from PCMCIA card
date and time not saved when power is off	no backup battery	connect a backup battery to the Multifunction connector

Troubleshooting a PC/104 System

If you have reviewed the preceeding table and still cannot isolate the problem with your cpuModule, please try the following troubleshooting steps. Even if the resulting information does not help you find the problem, it will be very helpful if you contact technical support.

Simplify the system. Remove items one at a time and see if one particular item seems to cause the problem.

Swap components. Try replacing items in the system one-at-a-time with similar items.

How to Obtain Technical Support

If after following the above steps, you still cannot resolve a problem with your cpuModule, please assemble the following information:

- cpuModule **model**, **BIOS version**, and serial number
- list of **all boards in system**
- list of settings from cpuModule Setup program
- printout of autoexec.bat and config.sys files (if applicable)
- description of problem
- circumstances under which problem occurs

Then contact factory technical support:

Phone: 814 234-8087

Fax: 814 234-5218

E-mail: techsupport@rtdusa.com

How to Return a Product

NOTE!	You *must* have authorization from the factory before returning *any* item for *any* reason!

If you wish to return a product to the factory for service, please follow this procedure:

1) Read the Limited Warranty to familiarize yourself with our warranty policy.
2) Contact the factory for a Return Merchandise Authorization (RMA) number.
3) **Write a detailed description** of the situation or problem.
   Include as much information as possible!
4) **List the name of a contact person**, familiar with technical details of the problem or situation, **along with their phone and fax numbers, address, and e-mail address** (if available).
5) **List your shipping address!!**
6) Indicate the shipping method you would like used to return the product to you.
   We will not ship by next-day service without your pre-approval.
7) Carefully package the product, *using proper anti-static packaging.*
8) Write the RMA number in large (1") letters on the outside of the package.
9) Return the package to:

   Real Time Devices

   200 Innovation Blvd.

   State College PA 16803

   USA

CHAPTER 8: LIMITED WARRANTY

Real Time Devices, Inc. warrants the hardware and software products it manufactures and produces to be free from defects in materials and workmanship for one year following the date of shipment from REAL TIME DEVICES. This warranty is limited to the original purchaser of product and is not transferable.

During the one year warranty period, REAL TIME DEVICES will repair or replace, at its option, any defective products or parts at no additional charge, provided that the product is returned, shipping prepaid, to REAL TIME DEVICES. All replaced parts and products become the property of REAL TIME DEVICES. Before returning any product for repair, customers are required to contact the factory for an RMA number.

THIS LIMITED WARRANTY DOES NOT EXTEND TO ANY PRODUCTS WHICH HAVE BEEN DAMAGED AS A RESULT OF ACCIDENT, MISUSE, ABUSE (such as: use of incorrect input voltages, improper or insufficient ventilation, failure to follow the operating instructions that are provided by REAL TIME DEVICES, "acts of God" or other contingencies beyond the control of REAL TIME DEVICES), OR AS A RESULT OF SERVICE OR MODIFICATION BY ANYONE OTHER THAN REAL TIME DEVICES. EXCEPT AS EXPRESSLY SET FORTH ABOVE, NO OTHER WARRANTIES ARE EXPRESSED OR IMPLIED, INCLUDING, BUT NOT LIMITED TO, ANY IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE, AND REAL TIME DEVICES EXPRESSLY DISCLAIMS ALL WARRANTIES NOT STATED HEREIN. ALL IMPLIED WARRANTIES, INCLUDING IMPLIED WARRANTIES FOR MECHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE, ARE LIMITED TO THE DURATION OF THIS WARRANTY. IN THE EVENT THE PRODUCT IS NOT FREE FROM DEFECTS AS WARRANTED ABOVE, THE PURCHASER'S SOLE REMEDY SHALL BE REPAIR OR REPLACEMENT AS PROVIDED ABOVE. UNDER NO CIRCUMSTANCES WILL REAL TIME DEVICES BE LIABLE TO THE PURCHASER OR ANY USER FOR ANY DAMAGES, INCLUDING ANY INCIDENTAL OR CONSEQUENTIAL DAMAGES, EXPENSES, LOST PROFITS, LOST SAVINGS, OR OTHER DAMAGES ARISING OUT OF THE USE OR INABILITY TO USE THE PRODUCT.

SOME STATES DO NOT ALLOW THE EXCLUSION OR LIMITATION OF INCIDENTAL OR CONSEQUENTIAL DAMAGES FOR CONSUMER PRODUCTS, AND SOME STATES DO NOT ALLOW LIMITATIONS ON HOW LONG AN IMPLIED WARRANTY LASTS, SO THE ABOVE LIMITATIONS OR EXCLUSIONS MAY NOT APPLY TO YOU.

THIS WARRANTY GIVES YOU SPECIFIC LEGAL RIGHTS, AND YOU MAY ALSO HAVE OTHER RIGHTS WHICH VARY FROM STATE TO STATE.